

## **A New Approach to Automatic Generation of All Triangular Mesh For Finite Element Analysis**

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### **Abstract**

This paper presents a new mesh generation method for a convex polygonal domain. We first decompose the convex polygon into simple sub regions in the shape of triangles. These simple regions are then triangulated to generate a mesh of 6-node triangular elements. We propose then an automatic 6-node triangular to 3-node triangular conversion scheme. Each isolated 6-node triangle is split into four triangles according to the usual scheme, that is, by adding three vertices in the middle of the edges and joining them by straight lines. To preserve the mesh conformity a similar procedure is also applied to every triangle of the domain to fully discretize the given convex polygonal domain into all triangles, thus propagating uniform refinement. This simple method generates a high quality mesh whose elements conform well to the requested shape by refining the problem domain. Examples are presented to illustrate the simplicity and efficiency of the new mesh generation method for standard and arbitrary shaped polygonal domains and cracked polygonal domains. We have appended MATLAB programs which incorporate the mesh generation scheme developed in this paper. These programs provide valuable output on the nodal coordinates, element connectivity and graphic display of the all triangular mesh for application to finite element analysis.

Keywords: finite elements, triangulation, all triangular mesh generation, convex polygonal domain, cracked convex polygonal domain, uniform refinement

### **1. Introduction**

The finite element method (FEM) is now used as a general purpose method applicable to all kinds of partial differential equations. The advent of modern computer technologies provided a powerful tool in numerical simulations for a range of problems in partial differential equations over arbitrary complex domains. A mesh is required for finite element method as it uses finite elements of a domain for analysis. Finite Element Analysis (FEA) is widely used in many fields including structures and optimization. The FEA in engineering applications comprises three phases: domain discretization, equation solving and error analysis. The domain discretization or mesh generation is the preprocessing phase which plays an important role in the achievement of accurate solutions.

FEM requires dividing the analysis region into many sub regions. These small regions are the elements which are connected with adjacent elements at their nodes. Mesh generation is a procedure of generating the

geometric data of the elements and their nodes, and involves computing the coordinates of nodes, defining their connectivity and thus constructing the elements. Hence mesh designates aggregates of elements nodes and lines representing their connectivity. Though the FEM is a powerful and versatile tool, its usefulness is often hampered by the need to generate a mesh. Creating a mesh is the first step in a wide range of applications, including scientific and engineering computing and computer graphics. But generating a mesh can be very time consuming and prone to error if done manually. In recognition of this problem a large number of methods have been devised to automate the mesh generation task. An attempt to create a fully automatic mesh generator that is capable of generating a valid finite element meshes over arbitrary complex domains and needs only the information of the specified geometric boundary of the domain and the element size, started from the pioneering work [1] in the early 1970's. Since then many methodologies have been proposed and different algorithms have been devised in the development of automatic mesh generators [2-4]. In order to perform a reliable finite element simulation a number of researchers [5-7] have made efforts to develop adaptive FEA method which integrates with error estimation and automatic mesh modification. Traditionally adaptive mesh generation process is started from coarse mesh which gives large discretization error levels and takes a lot of iterations to get a desired final mesh. The research literature on the subject is vast and different techniques have been proposed [8]. As several engineering applications to real world problems cannot be defined on a rectangular domain or solved on a structured square mesh. The description and discretization of the design domain geometry, specification of the boundary conditions for the governing state equation, and accurate computation of the design response may require the use of unstructured meshes.

An unstructured simplex mesh requires a choice of mesh points (vertex nodes ) and triangulation. Many mesh generators produce a mesh of triangles by first creating all the nodes and then connecting nodes to form of triangles. The question arises as to what is the 'best' triangulation on a given set of points. One particular scheme, namely Delaunay triangulation [8], is considered by many researchers to be most suitable for finite element analysis. If the problem domain is a subset of the Cartesian plane, triangular or quadrilateral meshes are typically employed.

In this paper, we present a novel mesh generation scheme of all triangular elements for convex polygonal domains. This scheme converts the elements in background triangular mesh into triangles through the operation of splitting. We first decompose the convex polygon into simple subregions in the shape of triangles. These simple subregions are then triangulated to generate a fine mesh of 6-node triangles. We propose then an automatic 6-node triangular to 3-node triangular conversion scheme in which each isolated triangle is split into four triangles according to the usual scheme, that is by adding three vertices in the middle of edges and then joining these three vertices by straight lines. Further, to preserve the mesh conformity a similar procedure is also applied to every triangle of the domain and this fully discretizes the given convex polygonal domain into all 3-node triangles, thus propagating uniform refinement. In section 2 of this paper, we present a scheme to discretize the arbitrary and standard triangles into a fine mesh of 6-node triangular elements. In section 3, we explain the procedure to split each of these 6-node triangles into four 3-node triangles. In section 4, we have presented a method of piecing together of all triangular subregions and eventually creating an all triangular mesh for the given convex polygonal domain. In section 5, we present several examples to illustrate the simplicity and efficiency of the proposed mesh generation method for standard and arbitrary triangles, rectangles, squares, convex and cracked convex polygonal domains.

## 2. Division of an Arbitrary Triangle

We can map an arbitrary triangle with vertices  $(x_i, y_i)$ ,  $i = 1, 2, 3$  into a right isosceles triangle in the  $(u, v)$  space as shown in Fig. 1a, 1b. The necessary transformation is given by the equations.

$$x = x_1 + (x_2 - x_1)u + (x_3 - x_1)v$$

$$y = y_1 + (y_2 - y_1)u + (y_3 - y_1)v \quad (1)$$

The mapping of eqn.(1) describes a unique relation between the coordinate systems. This is illustrated by using the area coordinates and division of each side into three equal parts in Fig. 2a Fig. 2b. It is clear that all the coordinates of this division can be determined by knowing the coordinates  $(x_i, y_i)$ ,  $i = 1, 2, 3$  of the vertices for the arbitrary triangle. In general, it is well known that by making 'n' equal divisions on all sides and the concept of area coordinates, we can divide an arbitrary triangle into  $n^2$  smaller triangles having the same area which equals  $\Delta/n^2$  where  $\Delta$  is the area of a linear arbitrary triangle with vertices  $(x_i, y_i)$ ,  $i = 1, 2, 3$  in the Cartesian space.

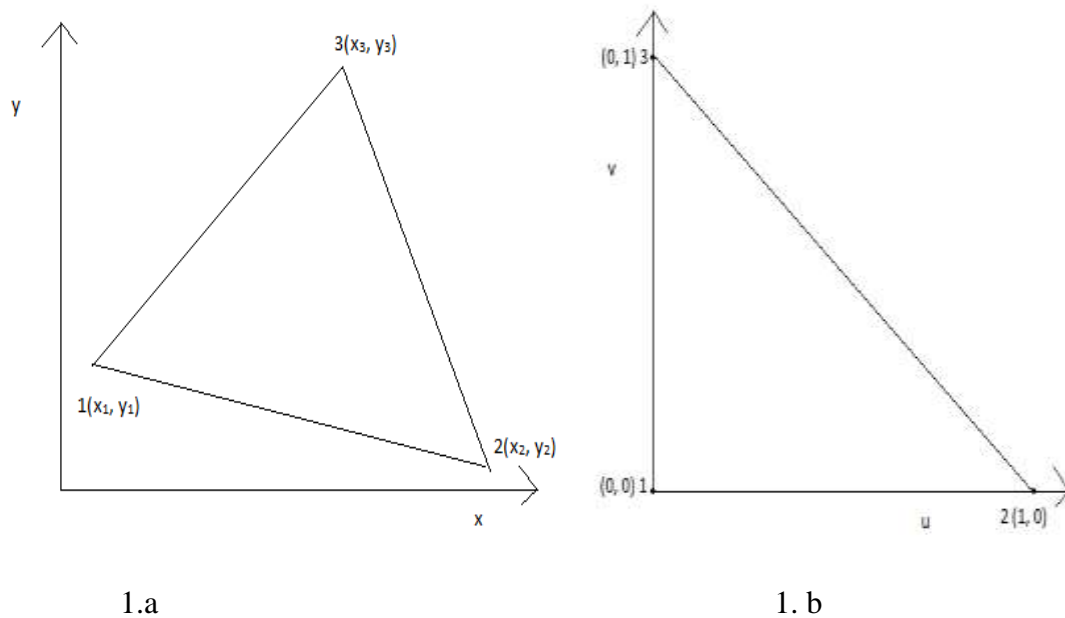


Fig. 1a An Arbitrary Linear Triangle in the  $(x, y)$  space

Fig. 1b A Right Isosceles Triangle in the  $(u, v)$

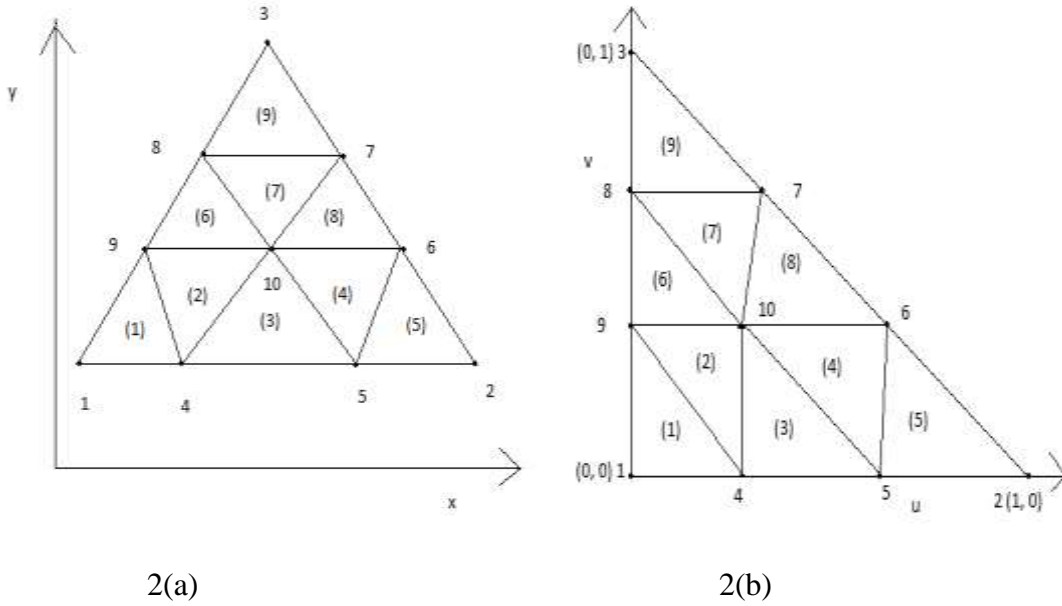


Fig. 2a Division of an arbitrary triangle into Nine triangles in Cartesian space Type equation here.

Fig. 2b Division of a right isosceles triangle into Nine right isosceles triangles in (u, v) space Type equation here.

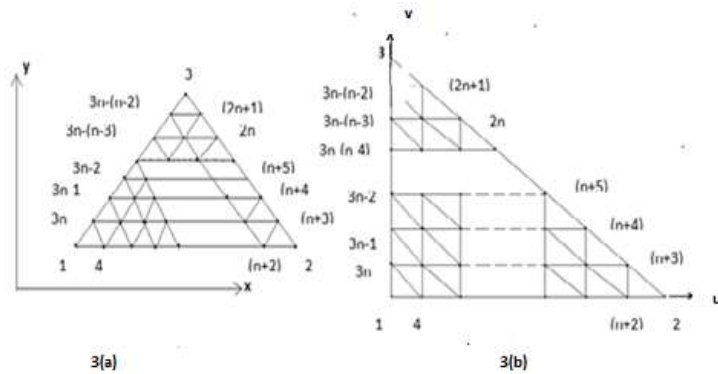


Fig. 3a Division of an arbitrary triangle with vertices  $((x_i, y_i), i = 1,2,3)$  into  $n^2$  triangle in Cartesian space  $(x, y)$ , where each side is divided into  $n$  divisions of equal length

Fig. 3b Division of a right isosceles triangle with vertices  $\{1(0,0),2(1,0),3(0,1)\}$  into  $n^2$  right isosceles triangle in  $(u, v)$  space, where each side is divided into  $n$  divisions of equal length

We have shown the division of an arbitrary triangle in Fig. 3a , Fig. 3b, We divided each side of the triangles (either in Cartesian space or natural space) into  $n$  equal parts and draw lines parallel to the sides of the triangles. This creates  $(n+1)(n+2)/2$  nodes. These nodes are numbered from triangle base line  $l_{12}$  ( letting  $l_{ij}$  as the line joining the vertex  $(x_i, y_i)$  and  $(x_j, y_j)$ ) along the line  $v = 0$  and upwards up to the line  $v = 1$  . The nodes 1, 2, 3 are numbered anticlockwise and then nodes 4, 5, -----,  $(n+2)$  are along line  $v = 0$  and the nodes  $(n+3)$ ,  $(n+4)$ , -----,  $2n$ ,  $(2n+1)$  are numbered along the line  $l_{23}$  i.e.  $u + v = 1$  and then the node  $(2n+2)$ ,  $(2n+3)$ , -----,  $3n$  are numbered along the line  $u = 0$ . Then the interior nodes are numbered in increasing order from left to right along the line  $v = \frac{1}{n}, \frac{2}{n}, \dots, \frac{n-1}{n}$  bounded on the right by the line

$+v = 1$  . Thus the entire triangle is covered by  $(n+1)(n+2)/2$  nodes. This is shown in the  $rr$  matrix of size  $(n+1) \times (n+1)$  , only nonzero entries of this matrix refer to the nodes of the triangles

$$rr = \begin{bmatrix} 1, & 4, & 5, & \dots, & (n+2), & 2 \\ 3n, & (3n+1), & \dots, & \dots, & 3n+(n-2), & (n+3), & 0 \\ 3n-1, & 3n+(n-1), & \dots, & \dots, & 3n+(n-2)+(n-3), & (n+4), & 0, & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 3n-(n-3), & \frac{(n+1)(n+2)}{2}, & 2n, & 0, & \dots, & \dots, & \dots, & 0 \\ 3n-(n-2), & (2n+1), & 0, & 0, & \dots, & \dots, & \dots, & 0 \\ 3, & 0, & 0, & 0, & \dots, & \dots, & \dots, & 0 \end{bmatrix}$$

-----(2)

### 3. Triangulation of an Arbitrary Triangle

We now consider the quadrangulation of an arbitrary triangle. We first divide the arbitrary triangle into a number of equal size six node triangles. Let us define  $l_{ij}$  as the line joining the points  $(x_i, y_i)$  and  $(x_j, y_j)$  in the Cartesian space  $(x, y)$ . Then the arbitrary triangle with vertices at  $((x_i, y_i), i = 1,2,3)$  is bounded by three lines  $l_{12}, l_{23},$  and  $l_{31}$  . By dividing the sides  $l_{12}, l_{23}, l_{31}$  into  $n = 2m$  divisions (  $m$ , an integer ) creates  $m^2$  six node triangular divisions. Then joining by straight lines the midpoints of the sides, we obtain four new triangles for each of these six node triangles. We have illustrated this process for the two and four divisions of  $l_{12}, l_{23},$  and  $l_{31}$  sides of the arbitrary and standard triangles in Figs. 4 and 5

#### 3.1 Two Divisions of Each side of an Arbitrary Triangle and Standard Triangle

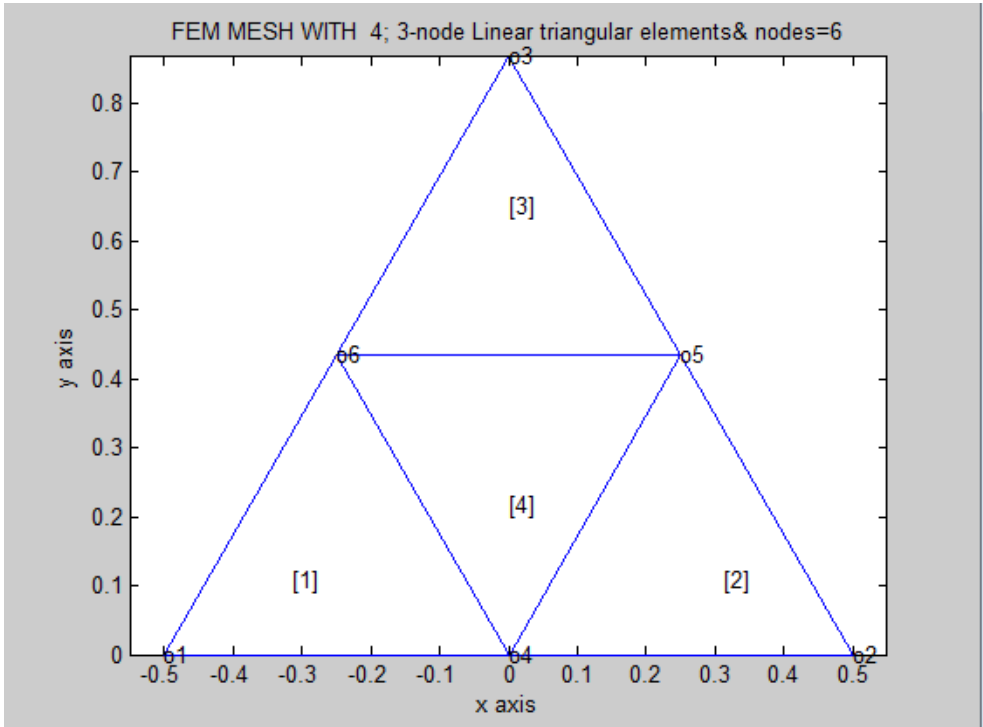


Fig 4(a)

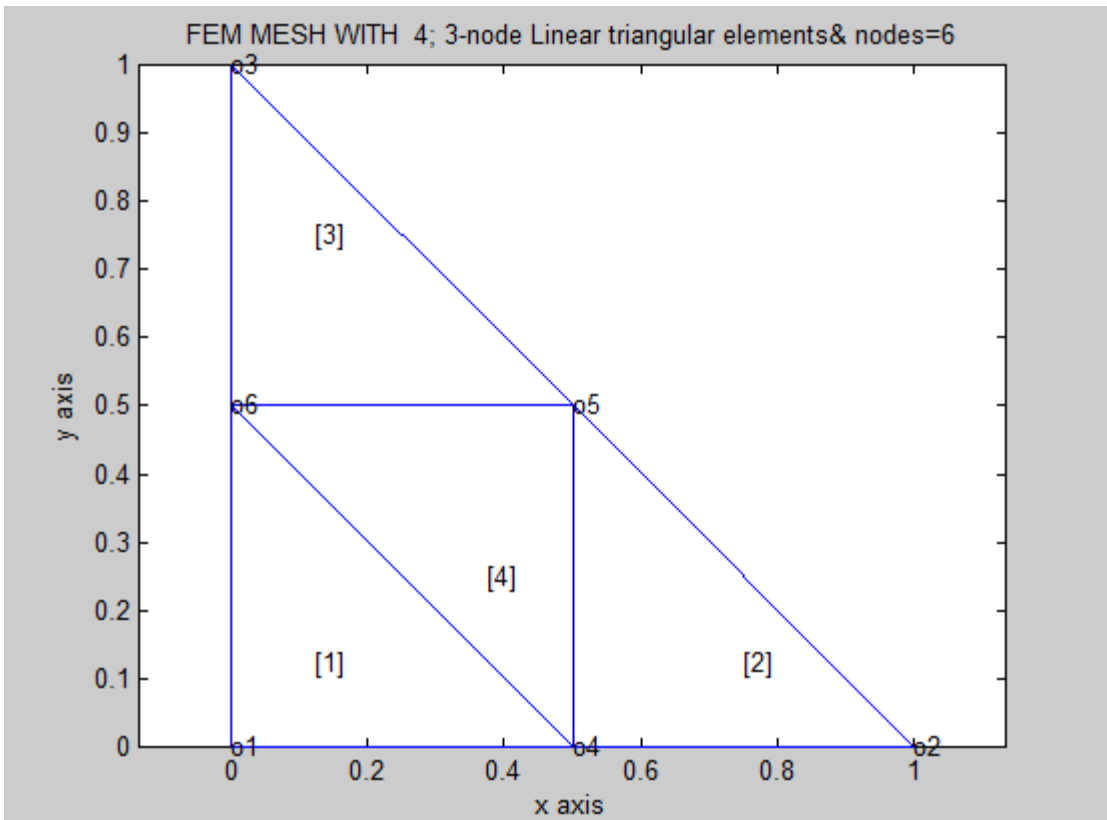


Fig.4(b)

Fig 4(a). Division of an arbitrary triangle into four triangles

Fig 4(b). Division of a standard triangle into four triangles

### 3.2 Four Divisions of Each side of an Arbitrary Triangle and Standard Triangle

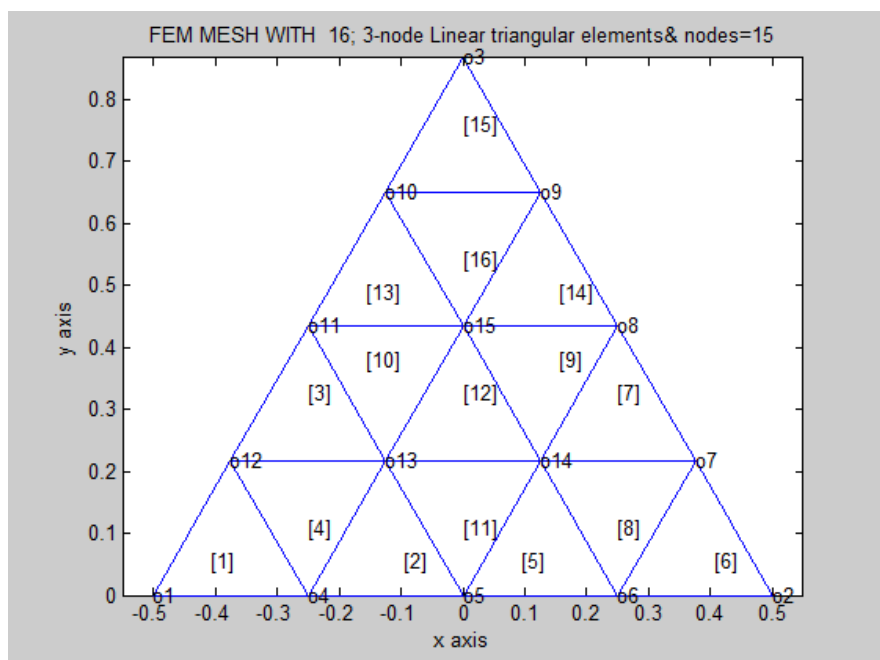


Fig.5(a)

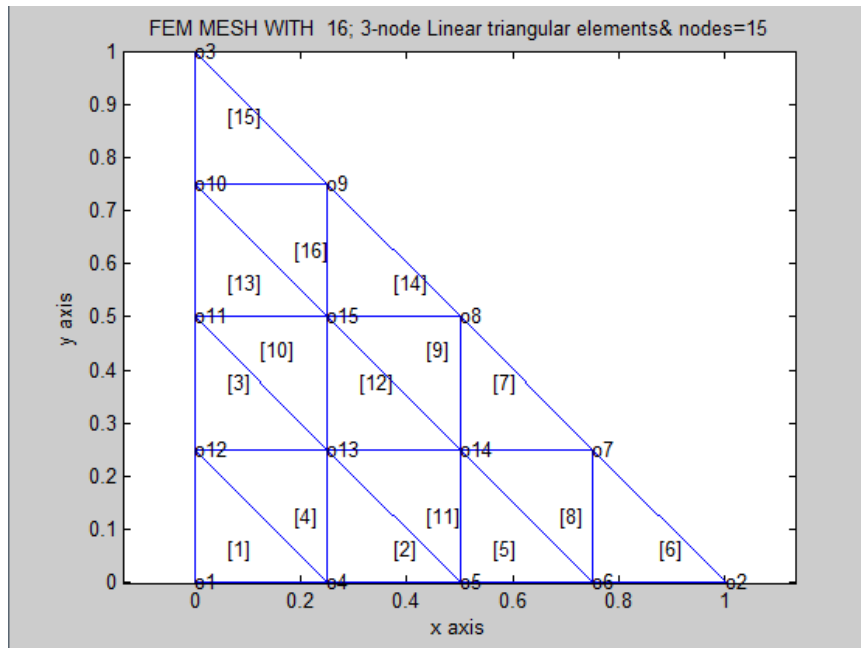


Fig.5(b)

Fig 5(a). Division of an arbitrary triangle into 4 six node arbitrary triangles which give rise to 16, three node arbitrary triangles

Fig 5(b). Division of a standard triangle into 4 six node right isosceles triangles which give rise to 16, three node right isosceles triangles

In general, we note that to divide an arbitrary triangle into equal size six node triangle, we must divide each side of the triangle into an even number of divisions and locate points in the interior of triangle at equal spacing. We also do similar divisions and locations of interior points for the standard triangle. Thus  $n$  (even) divisions creates  $(n/2)^2$  six node triangles in both the spaces. If the entries of the sub matrix  $\underline{rr}(i; i+2, j; j+2)$  are nonzero then two six node triangles can be formed. If  $\underline{rr}(i+1, j+2) = \underline{rr}(i+2, j+1; j+2) = 0$  then one six node triangle can be formed. If the sub matrices  $\underline{rr}(i; i+2, j; j+2)$  is a  $(3 \times 3)$  zero matrix, we cannot form the six node triangles. We now explain the creation of the six node triangles using the  $\underline{rr}$  matrix of eqn.(2). We can form six node triangles by using node points of three consecutive rows and columns of  $\underline{rr}$  matrix. This procedure is depicted in Fig. 6a for three consecutive rows  $i, i+1, i+2$  and three consecutive columns  $j, j+1, j+2$  of the  $\underline{rr}$  sub matrix Formation of six node triangle using sub matrix  $\underline{rr}$

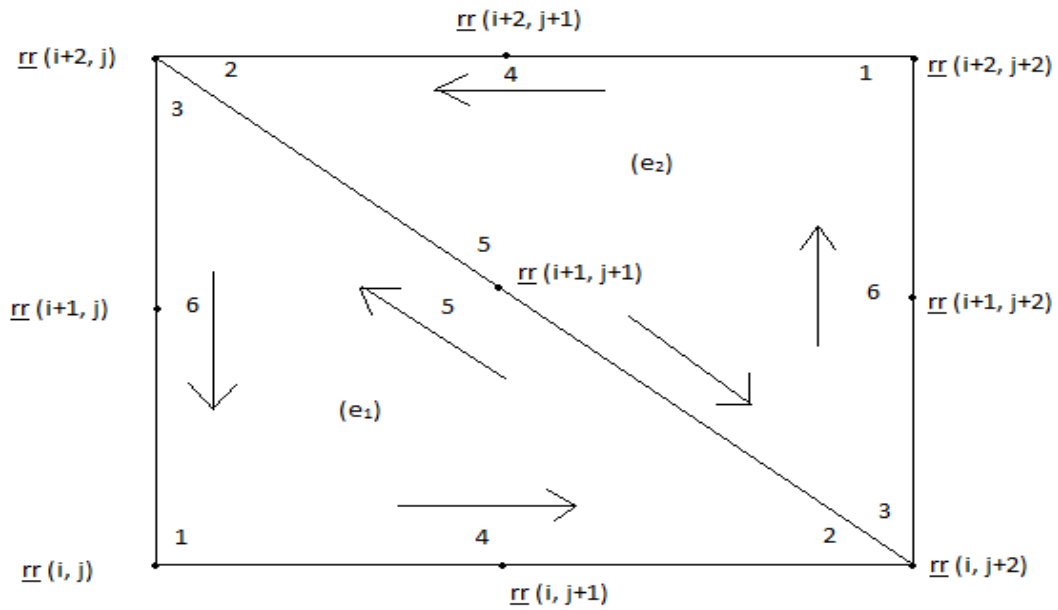


Fig. 6a Six node triangle formation for non zero sub matrix  $rr$

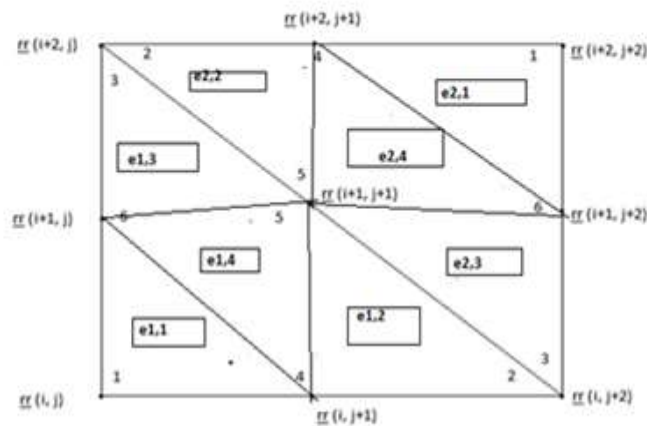


Fig. 6b Formation of 3-node triangles for non zero sub matrix  $rr$

If the sub matrix  $(rr(k, l), k = i, i + 1, i + 2, l = j, j + 1, j + 2)$  is nonzero, then we can construct two six node triangles. The element nodal connectivity is then given by

$$(e_1) < rr(i, j), rr(i, i + 2), rr(i + 2, j), rr(i, j + 1), rr(i + 1, j + 1), rr(i + 1, j) >$$

$$(e_2) < rr(i + 2, j + 2), rr(i + 2, j), rr(i, j + 2), rr(i + 2, j + 1), rr(i + 1, j + 1), rr$$

$$(i + 1, j + 2) > \text{-----}(3)$$



If the elements of sub matrix (  $\underline{rr} ( k,l), k = i, i + 1, i + 2), l = j, j + 1, j + 2$ ) are nonzero, then as stated earlier, we can construct two six node triangles. We can create four 3-node triangles in each of these six node triangles ( $e_1$ ) and ( $e_2$ ). This procedure is depicted in Fig.6b, The nodal connectivity for the four 3-node triangles created in ( $e_1$ ) and having element number  $n_1$  are given as

$$\begin{aligned}
 e1,1 &= T_{4n_1-3} < \underline{rr} (i, j), \underline{rr} (i, j + 1), \underline{rr} (i + 1, j) > \\
 e1,2 &= T_{4n_1-2} < \underline{rr} (i, j + 2), \underline{rr} (i + 1, j + 1), \underline{rr} (i, j + 1) > \\
 e1,3 &= T_{4n_1-1} < \underline{rr} (i + 2, j), \underline{rr} (i + 1, j), \underline{rr} (i + 1, j + 1) > \\
 e1,4 &= T_{4n_1} < \underline{rr} (i, j + 1), \underline{rr} (i + 1, j + 1), \underline{rr} (i + 1, j) >
 \end{aligned}
 \tag{4}$$

and the nodal connectivity for the 4 triangles created in ( $e_2$ ) are given as

$$\begin{aligned}
 e2,1 &= T_{4n_2-3} < \underline{rr} (i + 2, j + 2), \underline{rr} (i + 2, j + 1), \underline{rr} (i + 1, j + 2) > \\
 e2,2 &= T_{4n_2-2} < \underline{rr} (i + 2, j), \underline{rr} (i + 1, j + 1), \underline{rr} (i + 2, j + 1) > \\
 e2,3 &= T_{4n_2-1} < \underline{rr} (i, j + 2), \underline{rr} (i + 1, j + 2), \underline{rr} (i + 1, j + 1) > \\
 e2,4 &= T_{4n_2} < \underline{rr} (i + 2, j + 1), \underline{rr} (i + 1, j + 1), \underline{rr} (i + 1, j + 2) >
 \end{aligned}
 \tag{5}$$

#### 4. Triangulation of the Polygonal Domain

We can generate polygonal meshes by piecing together of the triangles with straight sides. We designate them as subregions(called LOOPS). The user specifies the shape of these LOOPS by designating six coordinates of each LOOP

As an example, consider the geometry shown in Fig. 7(a). This is a square region R which is simply chosen for illustration. We divide this region into four LOOPS as shown in Fig.7(d). These LOOPS 1,2,3 and 4 are triangles each with three sides. After the LOOPS are defined, the number of elements for each LOOP is selected to produce the mesh shown in Fig. 7(c).The complete mesh is shown in Fig.7(b)



Fig.7(a) Region R to be analyzed

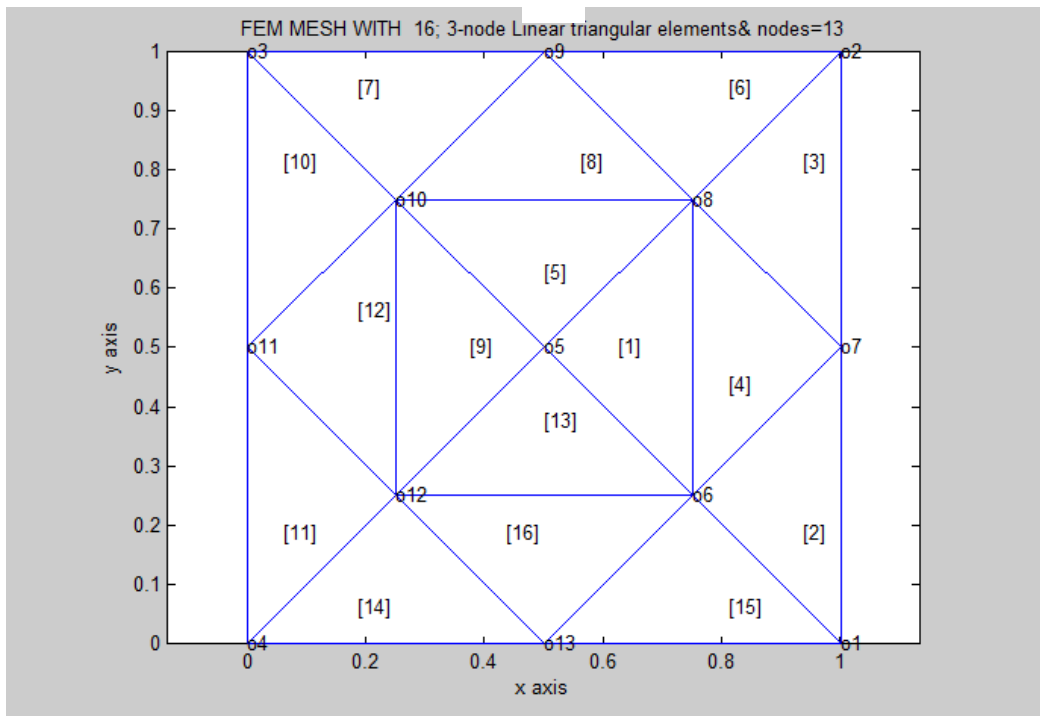
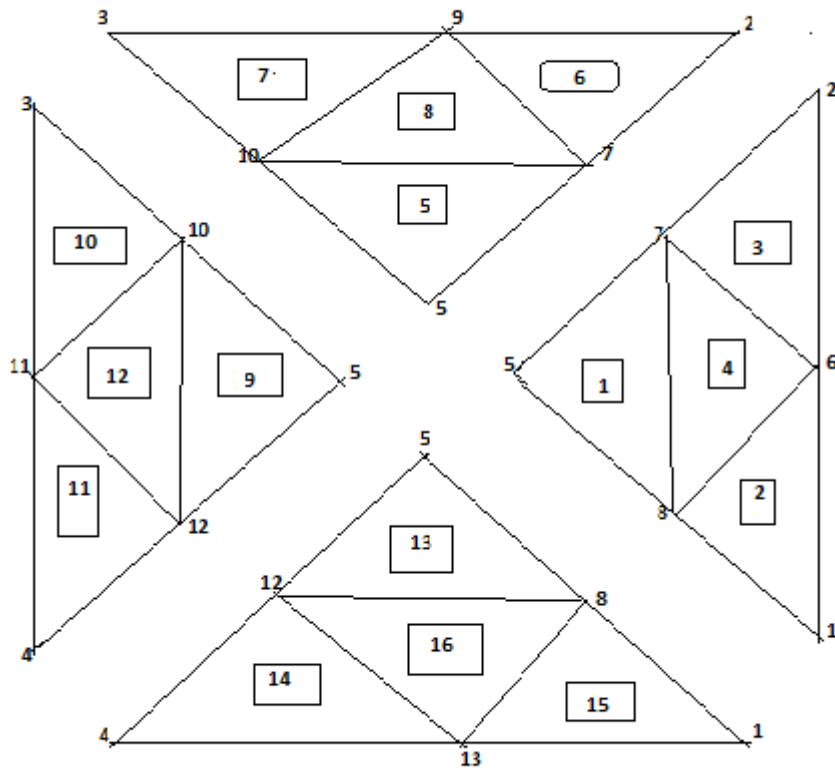
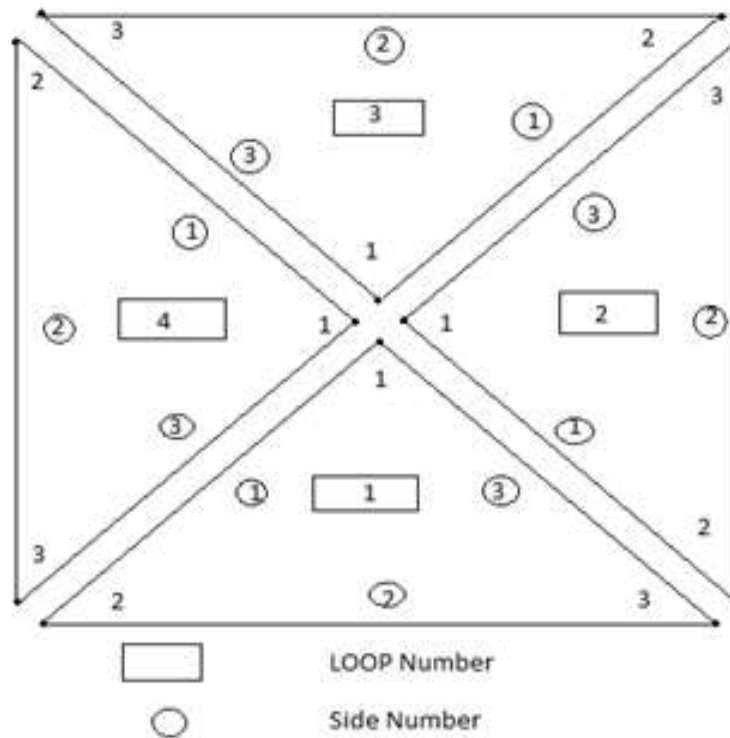


Fig.7(b) Example of completed mesh



7(c) Exploded view showing four loops



7(d) Example of a loop and side numbering scheme

#### 4 Mesh Generation Scheme for Convex Polygonal Domains

How to define the LOOP geometry, specify the number of elements and piece together the LOOPS will now be explained

**Joining LOOPS :** A complete mesh is formed by piecing together LOOPS. This piecing is done sequentially thus, the first LOOP formed is the foundation LOOP, with subsequent LOOPS joined either to it or to other LOOPS that have already been defined. As each LOOP is defined, the user must specify for each of the three sides of the current LOOP.

In the present mesh generation code, we aim to create a convex polygon. This requires a simple procedure. We join side 3 of LOOP 1 to side 1 of LOOP 2, side 3 of LOOP 2 will be joined to side 1 of LOOP 3, side 3 of LOOP 3 will be joined to side 1 of LOOP 4. Finally side 3 of LOOP 4 will be joined to side 1 of LOOP 1.

When joining two LOOPS, it is essential that the two sides to be joined have the same number of divisions. Thus the number of divisions remains the same for all the LOOPS. We note that the sides of LOOP ( $i$ ) and side of LOOP ( $i + 1$ ) share the same node numbers. But we have to reverse the sequencing of node numbers of side 3 and assign them as node numbers for side 1 of LOOP ( $i + 1$ ). This will be required for allowing the anticlockwise numbering for element connectivity

#### 5. Application Examples

### 5.1 Mesh Generation Over an Arbitrary Triangle

In applications to boundary value problems due to symmetry considerations, we may have to discretize an arbitrary triangle. Our purpose is to have a code which automatically generates triangulations of the domain by assuming the input as coordinates of the vertices. We use the theory and procedure developed in section 2 and section 3 of this paper for this purpose. The following MATLAB codes are written for this purpose.

- (1) triangulation4polygonal\_domain\_coordinates.m
- (2) nodaladdresses\_for4XnXn\_LinearTriangles.m
- (3) generate\_area\_coordinate\_over\_standard\_triangle.m
- (4) triangular\_mesh4LinearTriangles\_t3.m

We have included some meshes generated by using the above codes written in MATLAB. We illustrate the mesh generation for a standard triangle and an arbitrary triangle. Some sample commands to generate these meshes are included in comment lines. In all the codes sample input data is included for easy access.

### 5.2 Mesh Generation for a Convex Polygonal Domain

In several physical applications in science and engineering, the boundary value problem require meshes generated over convex polygons. Again our aim is to have a code which automatically generates a mesh of linear triangles for the complex domains such as those in [21,22]. We use the theory and procedure developed in sections 2, 3 and 4 for this purpose. The following MATLAB codes are written for this purpose.

- (1) triangular\_mesh4LinearTriangles\_t3.m
- (2) nodaladdresses\_for4XnXn\_LinearTriangles\_trial.m
- (3) triangulation4polygonal\_domain\_coordinates.m
- (4) generate\_area\_coordinate\_over\_standard\_triangle.m

We have included some meshes generated by using the above MATLAB codes. We further illustrate the application of above codes by generating meshes for a square, five sided and 20 sided regular convex polygons and cracked convex polygons. Some sample commands to generate the polygons stated above appear in the comment lines of programs. In all the cases the sample data is a part of the codes. The development of the MATLAB code is partly inspired by a procedure given in [23] and the literature available on the internet[24]

## 6 Conclusions

An automatic indirect triangular mesh generator which uses the splitting technique is presented for the two dimensional convex polygonal domains. This mesh generation is made fully automatic and allows the user to define the problem domain with minimum amount of input such as coordinates of boundary. Once this input is created, by selecting an appropriate interior point of the convex polygonal domain, we form the triangular subdomains. These subdomains are then triangulated to generate a fine mesh of six node triangular elements. We have then proposed an automatic 6-node triangular to 3-node triangular conversion scheme in which each isolated 6-node triangle is split into four 3-node triangles according to the usual scheme, adding three vertices in the middle of the edges and joining them by straight lines of the 6-node triangular element. This task is made a bit simple since a fine mesh of six node triangles is first

generated. Further, to preserve the mesh conformity a similar procedure is also applied to every triangle of the domain and this discretizes the given convex polygonal domain into all 3-node triangles, thus propagating a uniform refinement. This simple method generates high quality mesh whose elements conform well to the requested shape by refining the problem domain. We have also appended MATLAB programs which provide the nodal coordinates, element nodal connectivity and graphic display of the generated all triangular mesh for the standard triangle, an arbitrary triangle, a square and an arbitrary convex polygonal domain. We believe that this work will be useful for various applications in science and engineering.

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COMPUTER PROGRAMS IN MATLAB

```
%PROGRAM-(1) triangulation4polygonal_domain_coordinates.m
function[coord,gcoord,tnodes,nodetel,nnode,nel]=triangulation4polygonal_domain_coordinates(n1,n2,n3,nmax,numtri,n,mesh)
% n1=node number at(0,0)for a choosen triangle
% n2=node number at(1,0)for a choosen triangle
% n3=node number at(0,1)for a choosen triangle
% eln=6-node triangles with centroid
% spqd=4-node special convex quadrilateral
% n must be even,i.e.n=2,4,6,.....i.e number of divisions
% nmax=one plus the number of segments of the polygon
% nmax=the number of segments of the polygon plus a node interior to the polygon
% numtri=number of T6 triangles in each segment i.e a triangle formed by
% joining the end poits of the segment to the interior point(e.g:the centroid) of the polygon
% [eln,spqd]=nodaladdresses_special_convex_quadrilaterals_trial(n1=1,n2=2,n3=3,nmax=3,n=2,4,6,...)
% [eln,spqd]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1],[2;3;4;5],[3;4;5;2],5,1,2)
% [eln,spqd]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1],[2;3;4;5],[3;4;5;2],5,4,4)
% [eln,spqd]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1],[2;3;4;5],[3;4;5;2],5,9,6)
% [eln,spqd]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1],[2;3;4;5],[3;4;5;2],5,16,8)
% PARVIZ MOIN EXAMPLE
syms U V W xi yi

switch mesh
case 1% for MOIN POLYGON
x=sym([1/2;1/2;1; 1;1/2;0; 0;0])%for MOIN EXAMPLE
y=sym([1/2; 0;0;1/2; 1; 1;1/2;0])%for MOIN EXAMPLE

case 2% for a unit square: 0<=x,y<=1
x=sym([1/2;1/2;1; 1; 1;1/2;0; 0;0])%FOR UNIT SQUARE
y=sym([1/2; 0;0;1/2; 1; 1;1/2;0])%FOR UNIT SQUARE

case 3% for A POLYGON like MOIN OVER(-1/2)<=x,y<=(1/2)
% 1 2 3 4 5 6 7 8
```

```
x=sym([0; 0; 1/2;1/2; 0;-1/2;-1/2;-1/2])
y=sym([0;-1/2;-1/2; 0;1/2; 1/2; 0;-1/2])
```

```
case 4% for a unit square: -0.5<=x,y<=0.5
```

```
% 1 2 3 4 5 6 7 8
x=sym([0; 0; 1/2;1/2;1/2; 0;-1/2;-1/2;-1/2])
y=sym([0;-1/2;-1/2; 0;1/2;1/2; 1/2; 0;-1/2])
```

```
case 5% for a convex polygonsixside
```

```
% 1 2 3 4 5 6 7
x=sym([0.5;0.1;0.7;1;.75;.5;0])
y=sym([0.5;0;0.2;.5;.85;1;.25])
```

```
case 6% standard triangle
```

```
x=sym([0;1;0])
y=sym([0;0;1])
```

```
case 7% equilateral triangle
```

```
% x=sym([0;1;1/2])
% y=sym([0;0;sqrt(3)/2])
x=sym([-1/2;1/2;0])
y=sym([0;0;sqrt(3)/2])
```

```
case 8% for a convex polygonsixside
```

```
% 1 2 3 4 5 6 7 8
x=sym([0.5;0.1;0.7;1;.75;.5;.25;0])
y=sym([0.5;0;0.2;.5;.85;1;.625;.25])
```

```
case 9% for a convex polygeightside
```

```
% 1 2 3 4 5 6 7 8 9
x=(.2;0.5;.8;1.0;.75;0.5;0.25;0.0;0.5)
y=(.2;.05;.2;0.5;.85;1.0;0.90;0.6;0.5)
```

```
case 10
```

```
% 1 2 3 4 5 6 7 8 9
x=(0.5;.2;0.5;.8;1.0;.75;0.5;0.25;0.0)
y=(0.5;.2;.05;.2;0.5;.85;1.0;0.90;0.6)
```

```
case 11 % a square
```

```
% 1 2 3 4 5
% x=(0;1;1;0;0.5)
% y=(0;0;1;1;0.5)
% 1 2 3 4 5
x=sym([1;1;0;0;0.5])
y=sym([0;1;1;0;0.5])
```

```
case 12 % a 2-square [-1,1]x[-1,1]
```

```
% 1 2 3 4 5 6 7 8 9
x=sym([0; 0; 1; 1; 1; 0; -1; -1; -1])
y=sym([0; -1; -1; 0; 1; 1; 1; 0; -1])
```

```
case 13% for a unit square: 0<=x,y<=1
```

```
x=sym([1/2;1/2;1; 1; 1;1/2;0; 0;0])%FOR UNIT SQUARE
y=sym([1/2; 0;0;1/2; 1; 1;1;1/2;0])%FOR UNIT SQUARE
```

```
case 14% for a unit square: 0<=x,y<=1
```

```
x=sym([1/2;1/2;1; 1; 1;1/2;0; 0;0])%FOR UNIT SQUARE
y=sym([1/2; 0;0;1/2; 1; 1;1;1/2;0])%FOR UNIT SQUARE
```

```
case 15% for a unit square: 0<=x,y<=1
```

```
x=sym([1/2;1/2;1; 1; 1;1/2;0; 0;0])%FOR UNIT SQUARE
y=sym([1/2; 0;0;1/2; 1; 1;1;1/2;0])%FOR UNIT SQUAREpi
```

```
case 16 % a 2-square [-1,1]x[-1,1]
```

```
% 1 2 3 4 5 6 7 8 9
x=sym([0; 0; 1; 1; 1; 0; -1; -1; -1])
y=sym([0; -1; -1; 0; 1; 1; 1; 0; -1])
```

```
case 17% isosceles triangle(one triangle in a square-required for torsion analysis)
```

```
x=sym([0;sqrt(2)/2; -sqrt(2)/2])
y=sym([0;sqrt(2)/2;sqrt(2)/2])
```

```
case 18% isosceles triangle(torsion of an equilateral triangle,each side=2*sqrt(3))
```



```

x=sym([-sqrt(3);sqrt(3); 0])
y=sym([ -1; -1; 2])
case 19%triangle inscribed in a circle of radius=1(torsion of an equilateral triangle each side=sqrt(3))
x=sym([-sqrt(3)/2;sqrt(3)/2; 0])
y=sym([ -1/2; -1/2; 1])
case 20%square inscribed in a circle of radius=1,required for torsion analysis
% 1 2 3 4 5
x=sym([0;-sqrt(2)/2; sqrt(2)/2;sqrt(2)/2;-sqrt(2)/2])
y=sym([0;-sqrt(2)/2;-sqrt(2)/2;sqrt(2)/2; sqrt(2)/2])
case 21%regular pentagon inscribed in a circle of radius=1,required for torsion analysis
% 1 2 3 4 5 6
x=sym([0;cos(pi/10);0;-cos(pi/10);-cos(3*pi/10); cos(3*pi/10)])
y=sym([0;sin(pi/10);1; sin(pi/10);-sin(3*pi/10);-sin(3*pi/10)])
case 22%regular hexagon inscribed in a circle of radius=1,required for torsion analysis
% 1 2 3 4 5 6 7
x=sym([0;1;cos(pi/3);-cos(pi/3);-1; -cos(pi/3); cos(pi/3)])
y=sym([0;0;sin(pi/3); sin(pi/3); 0; -sin(pi/3);-sin(pi/3)])
case 23%regular heptagon inscribed in a circle of radius=1,required for torsion analysis
% 1 2 3 4 5 6 7 8
x=sym([0;-cos(5*pi/14); cos(5*pi/14); cos(pi/14);cos(3*pi/14);0;-cos(3*pi/14);-cos(pi/14)])
y=sym([0;-sin(5*pi/14);-sin(5*pi/14);-sin(pi/14);sin(3*pi/14);1; sin(3*pi/14);-sin(pi/14)])
case 24 %regular octagon inscribed in a circle of radius=1,required for torsion analysis
% 1 2 3 4 5 6 7 8 9
x=sym([0;1;cos(pi/4);0;-cos(pi/4);-1;-cos(pi/4); 0; cos(pi/4)])
y=sym([0;0;sin(pi/4);1; sin(pi/4); 0;-sin(pi/4);-1;-sin(pi/4)])
case 25%(9-gon)nonagon
% 1 2 3 4 5 6 7 8 9 10
x=sym([0;cos(pi/18); cos(5*pi/18);0;-cos(5*pi/18);-cos(pi/18);-cos(3*pi/18);-cos(7*pi/18); cos(7*pi/18); cos(3*pi/18)])
y=sym([0;sin(pi/18); sin(5*pi/18);1; sin(5*pi/18); sin(pi/18);-sin(3*pi/18);-sin(7*pi/18);-sin(7*pi/18);-sin(3*pi/18)])
case 26%(10-gon)decagon
% 1 2 3 4 5 6 7 8 9 10 11
x=sym([0;1;cos(pi/5); cos(2*pi/5);-cos(2*pi/5);-cos(pi/5);-1;-cos(pi/5);-cos(2*pi/5); cos(2*pi/5); cos(pi/5)])
y=sym([0;0;sin(pi/5); sin(2*pi/5); sin(2*pi/5); sin(pi/5); 0;-sin(pi/5);-sin(2*pi/5);-sin(2*pi/5);-sin(pi/5)])
case 27%(11-gon)hendecagon
% 1 2 3 4 5 6 7 8 9 10 11 12
x=sym([0;cos(3*pi/22);cos(7*pi/22);0;-cos(7*pi/22);-cos(3*pi/22);-cos(pi/22);-cos(5*pi/22);-cos(9*pi/22); cos(9*pi/22);
cos(5*pi/22); cos(pi/22)])
y=sym([0;sin(3*pi/22);sin(7*pi/22);1; sin(7*pi/22); sin(3*pi/22);-sin(pi/22);-sin(5*pi/22);-sin(9*pi/22);-sin(9*pi/22);-
sin(5*pi/22);-sin(pi/22)])
case 28%(12-gon)dodecagon
% 1 2 3 4 5 6 7 8 9 10 11 12 13
x=sym([0;1;cos(pi/6);cos(pi/3);0;-cos(pi/3);-cos(pi/6);-1;-cos(pi/6);-cos(pi/3); 0; cos(pi/3); cos(pi/6)])
y=sym([0;0;sin(pi/6);sin(pi/3);1; sin(pi/3); sin(pi/6); 0;-sin(pi/6);-sin(pi/3);-1;-sin(pi/3);-sin(pi/6)])
case 29%(13-gon)tridecagon
% 1 2 3 4 5 6 7 8 9 10 11 12 13 14
x=sym([0;cos(pi/26);cos(5*pi/26);cos(9*pi/26);0;-cos(9*pi/26);-cos(5*pi/26);-cos(pi/26);-cos(3*pi/26);-cos(7*pi/26);-
cos(11*pi/26); cos(11*pi/26); cos(7*pi/26); cos(3*pi/26)])
y=sym([0;sin(pi/26);sin(5*pi/26);sin(9*pi/26);1; sin(9*pi/26); sin(5*pi/26); sin(pi/26);-sin(3*pi/26);-sin(7*pi/26);-
sin(11*pi/26);-sin(11*pi/26);-sin(7*pi/26);-sin(3*pi/26)])
case 30%(14-gon)tetradecagon
% 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
x=sym([0;1;cos(2*pi/14);cos(4*pi/14);cos(6*pi/14);-cos(6*pi/14);-cos(4*pi/14);-cos(2*pi/14);-1;-cos(2*pi/14);-cos(4*pi/14);-
cos(6*pi/14); cos(6*pi/14); cos(4*pi/14); cos(2*pi/14)])
y=sym([0;0;sin(2*pi/14);sin(4*pi/14);sin(6*pi/14); sin(6*pi/14); sin(4*pi/14); sin(2*pi/14); 0;-sin(2*pi/14);-sin(4*pi/14);-
sin(6*pi/14);-sin(6*pi/14);-sin(4*pi/14);-sin(2*pi/14)])
case 31%(15-gon)pentadecagon
% 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
16
x=sym([0; cos(pi/30);cos(3*pi/30);cos(7*pi/30);cos(11*pi/30);0;-cos(11*pi/30);-cos(7*pi/30);-cos(3*pi/30);-cos(pi/30);-
cos(5*pi/30);-cos(9*pi/30);-cos(13*pi/30); cos(13*pi/30); cos(9*pi/30); cos(5*pi/30)])
y=sym([0;-sin(pi/30);sin(3*pi/30);sin(7*pi/30);sin(11*pi/30);1; sin(11*pi/30); sin(7*pi/30); sin(3*pi/30);-sin(pi/30);-
sin(5*pi/30);-sin(9*pi/30);-sin(13*pi/30);-sin(13*pi/30);-sin(9*pi/30);-sin(5*pi/30)])
case 32%(16-gon)hexadecagon

```

```

% 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17
x=sym([0;1;cos(pi/8);cos(pi/4);cos(3*pi/8);0;-cos(3*pi/8);-cos(pi/4);-cos(pi/8);-1;-cos(pi/8);-cos(pi/4);-cos(3*pi/8); 0;
cos(3*pi/8); cos(pi/4); cos(pi/8)]);
y=sym([0;0;sin(pi/8);sin(pi/4);sin(3*pi/8);1; sin(3*pi/8); sin(pi/4); sin(pi/8); 0;-sin(pi/8);-sin(pi/4);-sin(3*pi/8);-1;-sin(3*pi/8);-
sin(pi/4);-sin(pi/8)]);
case 33%(17-gon)heptadecogon
% 1 2 3 4 5 6 7 8 9 10 11 12 13 14
15 16 17 18
x=sym([0;cos(pi/34);cos(5*pi/34);cos(9*pi/34);cos(13*pi/34);0;-cos(13*pi/34);-cos(9*pi/34);-cos(5*pi/34);-cos(pi/34);-
cos(3*pi/34);-cos(7*pi/34);-cos(11*pi/34);-cos(15*pi/34); cos(15*pi/34); cos(11*pi/34); cos(7*pi/34); cos(3*pi/34)]);
y=sym([0;sin(pi/34);sin(5*pi/34);sin(9*pi/34);sin(13*pi/34);1; sin(13*pi/34); sin(9*pi/34); sin(5*pi/34); sin(pi/34);-
sin(3*pi/34);-sin(7*pi/34);-sin(11*pi/34);-sin(15*pi/34);-sin(15*pi/34);-sin(11*pi/34);-sin(7*pi/34);-sin(3*pi/34)]);
case 34%(18-gon)octadecogon
% 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
16 17 18 19
x=sym([0;1;cos(4*pi/36);cos(8*pi/36);cos(12*pi/36);cos(16*pi/36);-cos(16*pi/36);-cos(12*pi/36);-cos(8*pi/36);-cos(4*pi/36);-
1;-cos(4*pi/36);-cos(8*pi/36);-cos(12*pi/36);-cos(16*pi/36); cos(16*pi/36); cos(12*pi/36); cos(8*pi/36); cos(4*pi/36)]);
y=sym([0;0;sin(4*pi/36);sin(8*pi/36);sin(12*pi/36);sin(16*pi/36); sin(16*pi/36); sin(12*pi/36); sin(8*pi/36); sin(4*pi/36); 0;-
sin(4*pi/36);-sin(8*pi/36);-sin(12*pi/36);-sin(16*pi/36);-sin(16*pi/36);-sin(12*pi/36);-sin(8*pi/36);-sin(4*pi/36)]);
case 35%(19-gon)enneadecogon
% 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
16 17 18 19 20
x=sym([0;cos(3*pi/38);cos(7*pi/38);cos(11*pi/38);cos(15*pi/38);0;-cos(15*pi/38);-cos(11*pi/38);-cos(7*pi/38);-cos(3*pi/38);-
cos(pi/38);-cos(5*pi/38);-cos(9*pi/38);-cos(13*pi/38);-cos(17*pi/38); cos(17*pi/38); cos(13*pi/38); cos(9*pi/38); cos(5*pi/38);
cos(pi/38)]);
y=sym([0;sin(3*pi/38);sin(7*pi/38);sin(11*pi/38);sin(15*pi/38);1; sin(15*pi/38); sin(11*pi/38); sin(7*pi/38); sin(3*pi/38);-
sin(pi/38);-sin(5*pi/38);-sin(9*pi/38);-sin(13*pi/38);-sin(17*pi/38);-sin(17*pi/38);-sin(13*pi/38);-sin(9*pi/38);-sin(5*pi/38);-
sin(pi/38)]);
case 36%(20-gon)icosagon
% 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17
18 19 20 21
x=sym([0;1;cos(pi/10);cos(2*pi/10);cos(3*pi/10);cos(4*pi/10);0;-cos(4*pi/10);-cos(3*pi/10);-cos(2*pi/10);-cos(pi/10);-1;-
cos(pi/10);-cos(2*pi/10);-cos(3*pi/10);-cos(4*pi/10); 0; cos(4*pi/10); cos(3*pi/10); cos(2*pi/10); cos(pi/10)]);
y=sym([0;0;sin(pi/10);sin(2*pi/10);sin(3*pi/10);sin(4*pi/10);1; sin(4*pi/10); sin(3*pi/10); sin(2*pi/10); sin(pi/10); 0;-sin(pi/10);-
sin(2*pi/10);-sin(3*pi/10);-sin(4*pi/10);-1;-sin(4*pi/10);-sin(3*pi/10);-sin(2*pi/10);-sin(pi/10)]);

case 50%isoscles triangle(torsion of an equilateral triangle,each side=1 unit)
x=sym([-1/2;1/2; 0])
y=sym([ 0; 0;sqrt(3)/2])

case 51%one special quadrilateral with centroid in a triangle(torsion of an equilateral triangle,each side=1 unit)
% 1 2 3 4 5
x=sym([ 0; 0; 1/4; 0; -1/4])
y=sym([7*sqrt(3)/24;sqrt(3)/6;sqrt(3)/4;sqrt(3)/2;sqrt(3)/4])
case 52
x=sym([0;1;1])
y=sym([0;0;1])
case 53
x=sym([0;1;0])
y=sym([0;1;1])
case 54
x=sym([0;1;1;0;-1; 0])
y=sym([0;0;1;1; 0;-1])
case 55
% 1 2 3 4 5 6
x=sym([0;-1; 1;2;0;-2])
y=sym([0;-1;-1;0;1; 0])

case 56
x=sym([0;1;1;0;-1])
y=sym([0;0;1;1;-1])

```

```

end
if (nmax>3)
%[eln,trielm,rrr,tnodes,nodetel]=nodaladdresses_for4XnXn_LinearTriangles_trial(n1,n2,n3,nmax,numtri,n);
[eln,trielm,rrr,tnodes,nodetel]=nodaladdresses_for4XnXn_LinearTriangles_trial(n1,n2,n3,nmax,numtri,n);
end
if (nmax==3)
    [eln,trielm,rrr,tnodes,nodetel]=nodaladdresses_for4XnXn_LinearTriangles(n);
end
[U,V,W]=generate_area_coordinate_over_the_standard_triangle(n);
ss1='number of 6-node triangles =';
[p1,q1]=size(eln);
disp([ss1 num2str(p1)])
%
eln
%
ss2='number of triangular elements&nodes per element =';
[nel,nnel]=size(tri elm);
disp([ss2 num2str(nel) ',' num2str(nnel)])
%
tri elm
%
nnode=max(max(tri elm));
ss3='number of nodes of the triangular domain& number of triangular elements=';
disp([ss3 num2str(nnode) ',' num2str(nel)])
    nitri=nmax-1;

if (nmax==3)
    nitri=1;
end
for itri=1:nitri
disp('vertex nodes of the itri triangle')
[n1(itri,1) n2(itri,1) n3(itri,1)]
x1=x(n1(itri,1),1)
x2=x(n2(itri,1),1)
x3=x(n3(itri,1),1)
%
y1=y(n1(itri,1),1)
y2=y(n2(itri,1),1)
y3=y(n3(itri,1),1)
rrr(:, :, itri)
U'
V'
W'
kk=0;
for ii=1:n+1
    for jj=1:(n+1)-(ii-1)
        kk=kk+1;
        mm=rrr(ii,jj,itri);
        uu=U(kk,1);vv=V(kk,1);ww=W(kk,1);
        xi(mm,1)=x1*ww+x2*uu+x3*vv;
        yi(mm,1)=y1*ww+y2*uu+y3*vv;
    end
end
[xi yi]
%add coordinates of centroid
ne=(n/2)^2;
% stdnode=kk;
%for iii=1+(itri-1)*ne:ne*itri
%kk=kk+1;
% node1=eln(iii,1)
% node2=eln(iii,2)
% node3=eln(iii,3)

```

```

% mm=eln(iii,7)
% xi(mm,1)=(xi(node1,1)+xi(node2,1)+xi(node3,1))/3;
% yi(mm,1)=(yi(node1,1)+yi(node2,1)+yi(node3,1))/3;
%end

end% for itri
N=(1:nnode)'
[N xi yi]
%
coord(:,1)=(xi(:,1));
coord(:,2)=(yi(:,1));
gcoord(:,1)=double(xi(:,1));
gcoord(:,2)=double(yi(:,1));
%disp(gcoord)

%=====
%PROGRAM-(2) nodaladdresses_for4XnXn_LinearTriangles.m

function[eln,trielm,rrr,tnodes,nodetel]=nodaladdresses_for4XnXn_LinearTriangles(n)
% we first generate 6-node triangles
%hence it is necessary that n is an even number,i.e: n=2,4,6,8.....etc
%this generates (n/2)^2 triangles with 6-nodes each
%in each six node triangle we can make 4-Linear Triangles
%standard triangle is divided into n^2 right isoscles
%triangles each of side length (1/n) units
%computes nodal connections of these right isiscles triangles
%assumes nodal addresses for the standard triangle has local nodes
%as {1,2,3} which correspond to global nodes {1,(n+1),(n+1)*(n+2)/2}
%respectively and then generates nodal addresses for
%six node triangles and special convex quadrilaterals
%eln=6-node triangles
%triel=3-node linear triangular elements created in 6-node triangle
%n=number of divisions of a side and n must be even,i.e.n=2,4,6,.....
%syms mst_tri x
%disp('vertex nodes of triangle')
elm(1,1)=1;
elm(n+1,1)=2;
elm((n+1)*(n+2)/2,1)=3;
%disp('vertex nodes of triangle')
%base edge
kk=3;
for k=2:n
    kk=kk+1;
    elm(k,1)=kk;
end
%disp('left edge nodes')
nni=1;
for i=0:(n-2)
    nni=nni+(n-i)+1;
    elm(nni,1)=3*n-i;
end
%disp('right edge nodes')
nni=n+1;
for i=0:(n-2)
    nni=nni+(n-i);
    elm(nni,1)=(n+3)+i;
end

%disp('interior nodes')
nni=1;jj=0;
for i=0:(n-3)
    nni=nni+(n-i)+1;

```

```

for j=1:(n-2-i)
    jj=jj+1;
    nnj=nni+j;
    elm(nnj,1)=3*n+jj;
end
end
%disp(elm)
%disp(length(elm))

jj=0;kk=0;
for j=0:n-1
    jj=j+1;
for k=1:(n+1)-j
    kk=kk+1;
    row_nodes(jj,k)=elm(kk,1);
end
end
row_nodes(n+1,1)=3;
%for jj=(n+1):-1:1
% (row_nodes(jj,:));
%end
%[row_nodes]
rr=row_nodes;

rr=row_nodes;
rr
rrr(:,1)=rr;

%rr
%disp('element computations')
if rem(n,2)==0
ne=0;N=n+1;

for k=1:2:n-1
N=N-2;
i=k;
for j=1:2:N
    ne=ne+1;
    eln(ne,1)=rr(i,j);
    eln(ne,2)=rr(i,j+2);
    eln(ne,3)=rr(i+2,j);
    eln(ne,4)=rr(i,j+1);
    eln(ne,5)=rr(i+1,j+1);
    eln(ne,6)=rr(i+1,j);
end%i
%me=ne
%N-2
if (N-2)>0
for jj=1:2:N-2
ne=ne+1;
eln(ne,1)=rr(i+2,jj+2);
eln(ne,2)=rr(i+2,jj);
eln(ne,3)=rr(i,jj+2);
eln(ne,4)=rr(i+2,jj+1);;
eln(ne,5)=rr(i+1,jj+1);
eln(ne,6)=rr(i+1,jj+2);
end%jj
end
end%k

```

```

end
%
%ne=(n/2)^2,the number of six node triangles
%for kk=1:ne
%[eln(kk,1:6)]
%end

%nnd=(n+1)*(n+2)/2;
%for kkk=1:ne
% nnd=nnd+1;
% eln(kkk,7)=nnd;
%end
%
%to generate special quadrilaterals
%mm=0;

%for iel=1:ne
% for jel=1:3
% mm=mm+1;
% switch jel
% case 1
% spqd(mm,1:4)=[eln(iel,7) eln(iel,6) eln(iel,1) eln(iel,4)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,2) eln(iel,3) eln(iel,1)];
% case 2
% spqd(mm,1:4)=[eln(iel,7) eln(iel,4) eln(iel,2) eln(iel,5)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,3) eln(iel,1) eln(iel,2)];
% case 3
% spqd(mm,1:4)=[eln(iel,7) eln(iel,5) eln(iel,3) eln(iel,6)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,1) eln(iel,2) eln(iel,3)];
% end% switch
% end
% end

%for mmm=1:mm
% spqd(:,1:4)
%end
%
%ss1='number of 6-node triangles with centroid=';
%[p1,q1]=size(eln);
%disp([ss1 num2str(p1)])
%
%eln
%
%ss2='number of 4-node special convex quadrilaterals =';
%[p2,q2]=size(spqd);
%disp([ss2 num2str(p2)])
%
%spqd
%generate 4-Linear triangles in a 6-node triangles,call these as stel
mm=0;mmm=0;
for iel=1:ne
for jel=1:4
%mm=mm+1;mmm=mmm+1;
switch jel
case 1
mm=mm+1;mmm=mmm+1;
trielm(mmm,1:3)=[eln(iel,1) eln(iel,4) eln(iel,6)];
tnodes(mmm,1:3)=trielm(mmm,1:3);
nodetel(mm,1:3)=[eln(iel,1) eln(iel,2) eln(iel,3)];

```

case 2

```
mm=mm+1;mmm=mmm+1;
trielm(mmm,1:3)=[eln(iel,2) eln(iel,5) eln(iel,4)];
tnodes(mmm,1:3)=trielm(mmm,1:3);
nodetel(mm,1:3)=[eln(iel,2) eln(iel,3) eln(iel,1)];
```

case 3

```
mm=mm+1;mmm=mmm+1;
trielm(mmm,1:3)=[eln(iel,3) eln(iel,6) eln(iel,5)];
tnodes(mmm,1:3)=trielm(mmm,1:3);
nodetel(mm,1:3)=[eln(iel,3) eln(iel,1) eln(iel,2)];
```

case 4

```
mmm=mmm+1;
trielm(mmm,1:3)=[eln(iel,4) eln(iel,5) eln(iel,6)];
tnodes(mmm,1:3)=trielm(mmm,1:3);
```

end%switch

end

end

eln

trielm

tnodes

nodetel

```
=====
%PROGRAM-(3) generate_area_coordinate_over_the_standard_triangle.m
function[U,V,W]=generate_area_coordinate_over_the_standard_triangle(n)
syms ui vi wi U V W
kk=0;
for j=1:n+1
    for i=1:(n+1)-(j-1)
        kk=kk+1;
        ui(i,j)=(i-1)/n;
        vi(i,j)=(j-1)/n;
        wi(i,j)=1-ui(i,j)-vi(i,j);
        U(kk,1)=ui(i,j);
        V(kk,1)=vi(i,j);
        W(kk,1)=wi(i,j);
    end
end
% ui
% vi
% wi
U'
V'
W'
```

```
=====
%PROGRAM 4: nodaladdresses_for4XnXn_LinearTriangles_trial.m
function[eln,trielm,rrr,tnodes,nodetel]=nodaladdresses_for4XnXn_LinearTriangles_trial(n1,n2,n3,nmax,numtri,n)
%function[eln,spqd,rrr,nodes,nodetel]=nodaladdresses_special_convex_quadrilaterals_trial(n1,n2,n3,nmax,numtri,n)
%n1=node number at(0,0)for a choosen triangle
%n2=node number at(1,0)for a choosen triangle
%n3=node number at(0,1)for a choosen triangle
%eln=6-node triangles with centroid
%spqd=4-node special convex quadrilateral
%n must be even,i.e.n=2,4,6,.....i.e number of divisions
%nmax=one plus the number of segments of the polygon
%nmax=the number of segments of the polygon plus a node interior to the polygon
%numtri=number of T6 triangles in each segment i.e a triangle formed by
%joining the end poits of the segment to the interior point(e.g:the centroid) of the polygon
%[eln,spqd]=nodaladdresses_special_convex_quadrilaterals_trial(n1=1,n2=2,n3=3,nmax=3,n=2,4,6,...)
%[eln,spqd,rrr,nodes,nodetel]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1],[2;3;4;5],[3;4;5;2],5,1,2)
%[eln,spqd,rrr,nodes,nodetel]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1],[2;3;4;5],[3;4;5;2],5,4,4)
%[eln,spqd,rrr,nodes,nodetel]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1],[2;3;4;5],[3;4;5;2],5,9,6)
```

```

%[eln,spqd,rrr,nodes,nodetel]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1;1],[2;3;4;5],[3;4;5;2],5,16,8)
%PARVIZ MOIN EXAMPLE
%[eln,spqd,rrr,nodes,nodetel]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1;1;1;1],[2;3;4;5;6;7;8],[3;4;5;6;7;8;2],8
,1,2)
%[eln,spqd,rrr,nodes,nodetel]=nodaladdresses_special_convex_quadrilaterals_trial([1;1;1;1;1;1],[2;3;4;5;6;7;8],[3;4;5;6;7;8;2],8
,4,4)
%syms mst_tri x
ne=0;

%nitri=nmax-1;
[nitri,cl]=size(n1)

for itri=1:nitri
    elm(1:(n+1)*(n+2)/2,1)=zeros((n+1)*(n+2)/2,1)
    elm(1,1)=n1(itri,1)
    elm(n+1,1)=n2(itri,1)
    elm((n+1)*(n+2)/2,1)=n3(itri,1)
    disp('vertex nodes of the itri triangle')
    [n1(itri,1) n2(itri,1) n3(itri,1)]
    if itri==1
        kk=nmax;
        for k=2:n
            kk=kk+1
            elm(k,1)=kk
        end
        disp('base nodes=')
        %elm(2:n)
        edgen1n2(1:n+1,itri)=elm(1:n+1,1)
    end% itri==1
    if itri>1
        elm(1:n+1,1)=edgen1n3(1:n+1,itri-1);
    end% if itri>1
    if itri==1
        lmax=nmax+3*(n-1);
    end% if itri==1
    if (itri>1)&(itri<nitri)
        lmax=nmax+2*(n-1);
    end% if (itri>1)&(itri<nitri)
    mmax=nmax;
    if itri==1
        mmax=max(max(edgen1n2(1:n+1,1)))
    end% f itri==1
    disp('right edge nodes')
    nni=n+1;hh=1;qq(1,1)=n2(itri,1);
    for i=0:(n-2)
        hh=hh+1;
        nni=nni+(n-i);
        elm(nni,1)=(mmax+1)+i;
        qq(hh,1)=(mmax+1)+i;
    end
    qq(n+1,1)=n3(itri,1);
    edgen2n3(1:n+1,itri)=qq;

    if itri<nitri
        disp('left edge nodes')
        nni=1;gg=1;pp(1,1)=n1(itri,1);
        for i=0:(n-2)
            gg=gg+1;
            nni=nni+(n-i)+1;
            elm(nni,1)=lmax-i;

```



```

    pp(gg,1)=lmax-i;
end
pp(n+1,1)=n3(itri,1);
edgen1n3(1:n+1,itri)=pp
end%if itri<nitri

%if itri==n
% elm(1:n+1,1)=edgen1n2(1:n+1,1)
%end

if itri==nitri
disp('left edge nodes')
nni=1;gg=1;
for i=0:(n-2)
    gg=gg+1;
    nni=nni+(n-i)+1;
    elm(nni,1)=edgen1n2(gg,1);
end
%pp(n+1,1)=n3(itri,1);
%edgen1n3(1:n+1,itri)=pp
end%if itri==nitri
if itri==nitri
lmax=max(max(edgen2n3(1:n+1,itri)));
end%if itri==nitri

%elm
disp('interior nodes')
nni=1;jj=0;
for i=0:(n-3)
    nni=nni+(n-i)+1;
    for j=1:(n-2-i)
        jj=jj+1;
        nnj=nni+j;
        elm(nnj,1)=lmax+jj;
        [nnj lmax+jj];
    end
end
%disp(elm);
%disp(length(elm));

jj=0;kk=0;
for j=0:n-1
    jj=jj+1;
    for k=1:(n+1)-j
        kk=kk+1;
        row_nodes(jj,k)=elm(kk,1);
    end
end
row_nodes(n+1,1)=n3(itri,1);
%for jj=(n+1):-1:1
% (row_nodes(jj,:));
%end
%[row_nodes]
rr=row_nodes;
rr
rrr(:,itri)=rr;
disp('element computations')
if rem(n,2)==0
N=n+1;

```

```

for k=1:2:n-1
N=N-2;
i=k;
for j=1:2:N
    ne=ne+1
    eln(ne,1)=rr(i,j);
    eln(ne,2)=rr(i,j+2);
    eln(ne,3)=rr(i+2,j);
    eln(ne,4)=rr(i,j+1);
    eln(ne,5)=rr(i+1,j+1);
    eln(ne,6)=rr(i+1,j);
end%j
%me=ne
%N-2
if (N-2)>0
for jj=1:2:N-2
ne=ne+1
eln(ne,1)=rr(i+2,jj+2);
eln(ne,2)=rr(i+2,jj);
eln(ne,3)=rr(i,jj+2);
eln(ne,4)=rr(i+2,jj+1);;
eln(ne,5)=rr(i+1,jj+1);
eln(ne,6)=rr(i+1,jj+2);
end%jj
end%if(N-2)>0
end%k

end% if rem(n,2)==0
ne
%for kk=1:ne
%[eln(kk,1:6)]
%end
%add node numbers for element centroids

nnd=max(max(eln))
%if (n>3)
%for kkk=1+(itri-1)*numtri:ne
% nnd=nnd+1;
% eln(kkk,7)=nnd;
%end
%end
%if n==2
%for kkk=itri:ne
% nnd=nnd+1;
% eln(kkk,7)=nnd;
%end
%end
%for kk=1:ne
%[eln(kk,1:7)]
%end
%to generate special quadrilaterals
%mm=0;

%for iel=1:ne
% for jel=1:3
% mm=mm+1;
% switch jel
% case 1
% spqd(mm,1:4)=[eln(iel,7) eln(iel,6) eln(iel,1) eln(iel,4)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,2) eln(iel,3) eln(iel,1)];
% case 2

```

```

% spqd(mm,1:4)=[eln(iel,7) eln(iel,4) eln(iel,2) eln(iel,5)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,3) eln(iel,1) eln(iel,2)];
% case 3
% spqd(mm,1:4)=[eln(iel,7) eln(iel,5) eln(iel,3) eln(iel,6)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,1) eln(iel,2) eln(iel,3)];
% end% switch
%end
%end
nmax=max(max(eln));
%nel=mm;
%
%ne
%spqd

end%itri

%generate 4-Linear triangles in a 6-node triangles,call these as stel
mm=0;mmm=0;
for iel=1:ne
    for jel=1:4
        %mm=mm+1;mmm=mmm+1;
        switch jel
            case 1
                mm=mm+1;mmm=mmm+1;
                trielm(mmm,1:3)=[eln(iel,1) eln(iel,4) eln(iel,6)];
                tnodes(mmm,1:3)=trielm(mmm,1:3);
                nodetel(mm,1:3)=[eln(iel,1) eln(iel,2) eln(iel,3)];
            case 2
                mm=mm+1;mmm=mmm+1;
                trielm(mmm,1:3)=[eln(iel,2) eln(iel,5) eln(iel,4)];
                tnodes(mmm,1:3)=trielm(mmm,1:3);
                nodetel(mm,1:3)=[eln(iel,2) eln(iel,3) eln(iel,1)];
            case 3
                mm=mm+1;mmm=mmm+1;
                trielm(mmm,1:3)=[eln(iel,3) eln(iel,6) eln(iel,5)];
                tnodes(mmm,1:3)=trielm(mmm,1:3);
                nodetel(mm,1:3)=[eln(iel,3) eln(iel,1) eln(iel,2)];
            case 4
                mmm=mmm+1;
                trielm(mmm,1:3)=[eln(iel,4) eln(iel,5) eln(iel,6)];
                tnodes(mmm,1:3)=trielm(mmm,1:3);

        end% switch
    end
end

eln
trielm
tnodes
nodetel

%to generate special quadrilaterals
%mm=0;

%for iel=1:ne
% for jel=1:3
% mm=mm+1;

```

```

% switch jel
% case 1
% spqd(mm,1:4)=[eln(iel,7) eln(iel,6) eln(iel,1) eln(iel,4)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,2) eln(iel,3) eln(iel,1)];
% case 2
% spqd(mm,1:4)=[eln(iel,7) eln(iel,4) eln(iel,2) eln(iel,5)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,3) eln(iel,1) eln(iel,2)];
% case 3
% spqd(mm,1:4)=[eln(iel,7) eln(iel,5) eln(iel,3) eln(iel,6)];
% nodes(mm,1:4)=spqd(mm,1:4);
% nodetel(mm,1:3)=[eln(iel,1) eln(iel,2) eln(iel,3)];
% end% switch
% end
% end

%for mmm=1:mm
% spqd(:,1:4)
%end
%
ss1='number of 6-node triangles =';
[p1,q1]=size(eln);
disp([ss1 num2str(p1)])
%
eln
%
ss2='number of linear triangular elements&nodes per element =';
[nel,nnel]=size(trielm);
disp([ss2 num2str(nel) ',' num2str(nnel)])
%
nnode=max(max(trielm));
ss3='number of nodes of the triangular domain& number of linear triangles =';
disp([ss3 num2str(nnode) ',' num2str(nel)])

%=====
%PROGRAM5 triangular_mesh4LinearTriangles_t3.m
function []=triangular_mesh4LinearTriangles_t3(n1,n2,n3,nmax,numtri,ndiv,mesh,xlength,ylength,ndelete)
% maximum number of nodes on the actual domain
%
%clf
%(1)=generate 2-D quadrilateral mesh
%for a rectangular shape of domain
%quadrilateral_mesh_q4(xlength,ylength)
%xnode=number of nodes along x-axis
%ynode=number of nodes along y-axis
%xzero=x-coord of bottom left corner
%yzero=y-coord of bottom left corner
%xlength=size of domain along x-axis
%ylength=size of domain along y-axis
%type=0 for closed polygonal domain
%type=1 for open polygonal domain
%quadrilateral_mesh4MOINEX_q4([1;1;1;1;1;1],[2;3;4;5;6;7;8],[3;4;5;6;7;8;2],8,1,2,1,1,1)
%quadrilateral_mesh4MOINEX_q4([1;1;1;1;1;1],[2;3;4;5;6;7;8],[3;4;5;6;7;8;2],8,4,4,1,1,1)
%quadrilateral_mesh4MOINEX_q4([1;1;1;1;1;1],[2;3;4;5;6;7;8],[3;4;5;6;7;8;2],8,9,6,1,1,1)
%triangular_mesh4LinearTriangles_t3([1;1;1;1;1;1],[2;3;4;5;6;7;8],[3;4;5;6;7;8;2],8,1,2,1,1,1)
%triangular_mesh4LinearTriangles_t3([1;1;1;1;1;1],[2;3;4;5;6;7;8;9],[3;4;5;6;7;8;9;2],9,1,2,2,1,1)
%quadrilateral_mesh4MOINEX_q4([1;1;1;1;1;1],[2;3;4;5;6;7;8;9],[3;4;5;6;7;8;9;2],9,1,2,2,1,1)
%quadrilateral_mesh4MOINEX_q4([1;1;1;1;1;1],[2;3;4;5;6;7;8;9],[3;4;5;6;7;8;9;2],9,4,4,2,1,1)
%quadrilateral_mesh4MOINEX_q4([1;1;1;1;1;1],[2;3;4;5;6;7;8;9],[3;4;5;6;7;8;9;2],9,9,6,2,1,1)
%quadrilateral_mesh4MOINEX_q4([1;1;1;1;1;1],[2;3;4;5;6;7;8;9],[3;4;5;6;7;8;9;2],9,1,2,4,1,1)
%quadrilateral_mesh4MOINEX_q4([9;9;9;9;9;9],[1;2;3;4;5;6;7;8],[2;3;4;5;6;7;8;1],9,1,2,9,1,1)

```



```

figure(ndiv/2)
NDEL=ndelete*4*numtri
NEL=nel-NDEL;
NNODE=max(max(tnodes(1:NEL,1:3)));
NNNODE=NNODE
if (ndelete>1)
NNNODE=NNODE-ndelete+1
end

for i=1:NEL
for j=1:nnel
x(1,j)=xcoord(tnodes(i,j),1);
y(1,j)=ycoord(tnodes(i,j),1);
end;%j loop
xvec(1,1:4)=[x(1,1),x(1,2),x(1,3),x(1,1)];
yvec(1,1:4)=[y(1,1),y(1,2),y(1,3),y(1,1)];
axis equal
%axis tight
rtext=0;
switch mesh
case 1
axis([0 xlength 0 ylength])
case 2
axis([0 xlength 0 ylength])
case 3
xl=xlength/2;yl=ylength/2;
axis([-xl xl -yl yl])
case 4
xl=xlength/2;yl=ylength/2;
axis([-xl xl -yl yl])
case 12
axis([-xlength xlength -ylength ylength])

case 17
axis([-xlength xlength 0 ylength])
rpoly=' one isosceles triangle in a square';
rtext=1;
case 18
axis([-2*xlength 2*xlength -ylength 2*ylength])
rpoly=' equilateral triangle';
rtext=1;
case 19
axis([-xlength xlength -ylength/2 ylength])
rpoly=' equilateral triangle';
rtext=1;

case 20
axis([-xlength xlength -ylength ylength])
rpoly=' square';
rtext=1;
case 21
axis([-xlength xlength -ylength ylength])
rpoly=' pentagon';
rtext=1;
case 22
axis([-xlength xlength -ylength ylength])
rpoly=' hexagon';
rtext=1;
case 23
axis([-xlength xlength -ylength ylength])
rpoly=' heptagon';
rtext=1;

```

```

case 24
axis([-xlength xlength -ylength ylength])
rpoly=' octagon';
rtext=1;
case 25
axis([-xlength xlength -ylength ylength])
rpoly=' nonadecagon';
rtext=1;
case 26
axis([-xlength xlength -ylength ylength])
rpoly=' decagon';
rtext=1;
case 27
axis([-xlength xlength -ylength ylength])
rpoly=' hendecagon';
rtext=1;
case 28
axis([-xlength xlength -ylength ylength])
rpoly=' dodecagon';
rtext=1;
case 29
axis([-xlength xlength -ylength ylength])
rpoly=' tridecagon';
rtext=1;
case 30
axis([-xlength xlength -ylength ylength])
rpoly=' tetradecagon';
rtext=1;
case 31
axis([-xlength xlength -ylength ylength])
rpoly=' pentadecagon';
rtext=1;
case 32
axis([-xlength xlength -ylength ylength])
rpoly=' hexadecagon';
rtext=1;
case 33
axis([-xlength xlength -ylength ylength])
rpoly=' heptadecagon';
rtext=1;
case 34
axis([-xlength xlength -ylength ylength])
rpoly=' octadecagon';
rtext=1;
case 35
axis([-xlength xlength -ylength ylength])
rpoly=' enneadecagon';
rtext=1;
case 36
axis([-xlength xlength -ylength ylength])
rpoly=' icosagon';
rtext=1;

end
plot(xvec,yvec);%plot element
hold on;
%place element number
if ndiv<=4
midx=mean(xvec(1,1:4))
midy=mean(yvec(1,1:4))
text(midx,midy,['I',num2str(i),']);
end

```

```

end;%i loop

xlabel('x axis')
ylabel('y axis')
st1='FEM MESH WITH ';
st2=num2str(NEL);
st3='; 3-node Linear ';
st4='triangular';
st5=' elements'
st6='& nodes='
st7=num2str(NNNODE);
title([st1,st2,st3,st4,st5,st6,st7])
%put node numbers
if ndiv<=4
for jj=1:NNODE
if (ndelete>1)&(jj<=(nmax-ndelete+1))
text(gcoord(jj,1),gcoord(jj,2),['o',num2str(jj)]);
GCOORD(jj,1:2)=gcoord(jj,1:2);
end

if (ndelete>1)&(jj>=(nmax+1))
text(gcoord(jj,1),gcoord(jj,2),['o',num2str(jj-ndelete+1)]);
GCOORD(jj-ndelete+1,1:2)=gcoord(jj,1:2);
end
if(ndelete==0)|(ndelete==1))
text(gcoord(jj,1),gcoord(jj,2),['o',num2str(jj)]);
GCOORD(jj,1:2)=gcoord(jj,1:2);
end
end
end
%
if ndiv>4
for jj=1:NNODE
if (ndelete>1)&(jj<=(nmax-ndelete+1))
%text(gcoord(jj,1),gcoord(jj,2),['o',num2str(jj)]);
GCOORD(jj,1:2)=gcoord(jj,1:2);
end

if (ndelete>1)&(jj>=(nmax-ndelete+1))
%text(gcoord(jj,1),gcoord(jj,2),['o',num2str(jj-ndelete+1)]);
GCOORD(jj-ndelete+1,1:2)=gcoord(jj,1:2);
end
if((ndelete==0)|(ndelete==1))
%text(gcoord(jj,1),gcoord(jj,2),['o',num2str(jj)]);
GCOORD(jj,1:2)=gcoord(jj,1:2);
end
end
end

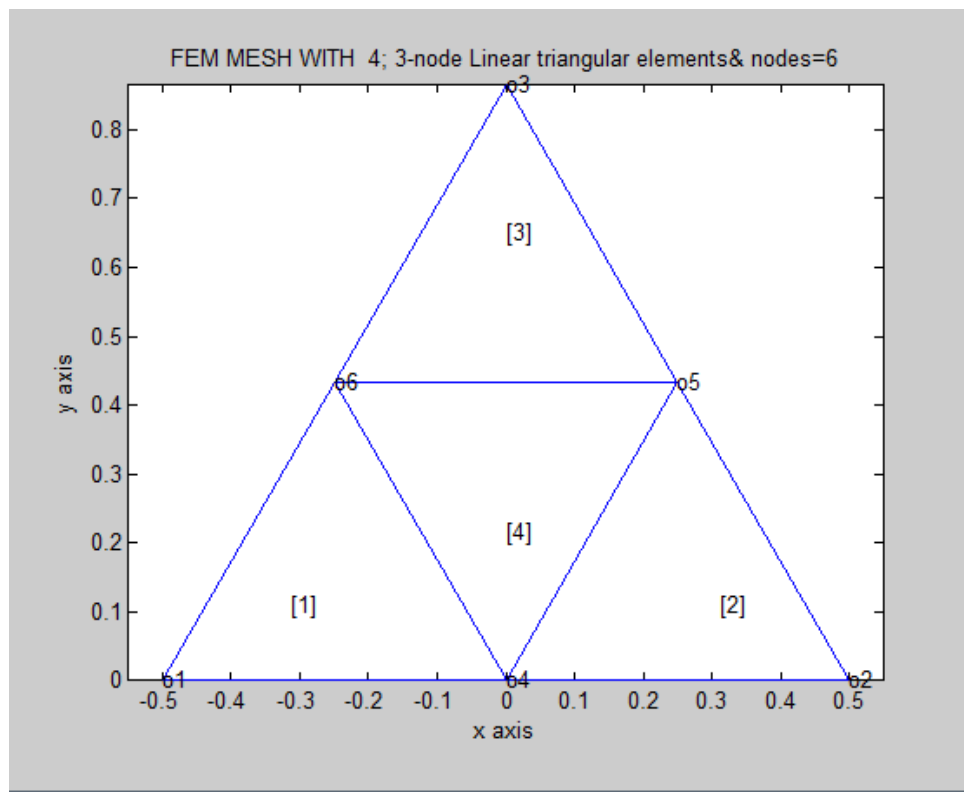
if rtext==1
text(0.1,-1.2,rpoly)
end
%axis off
NEL
NNNODE
GCOORD
%element nodal connectivity matrix
if (ndelete>1)
nnmax=nmax-(ndelete-1)

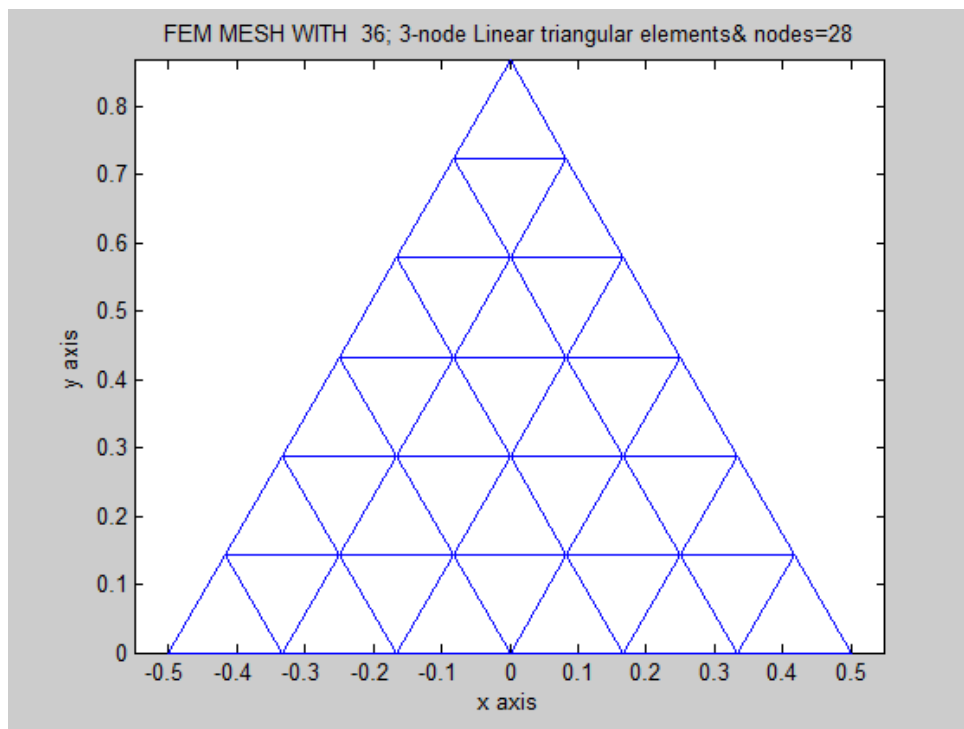
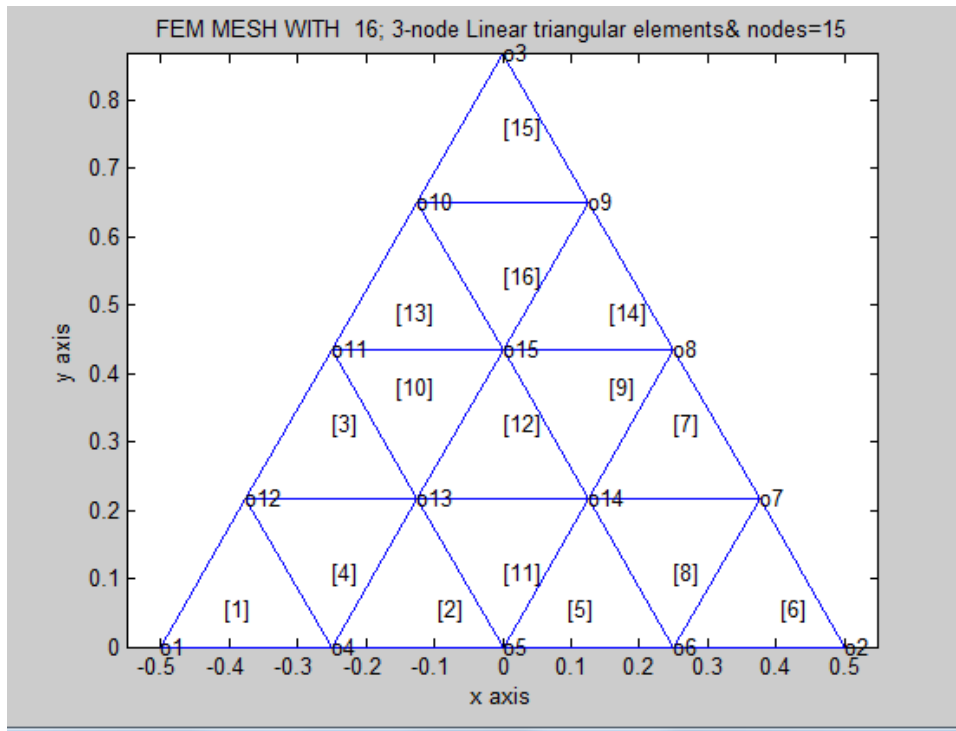
```

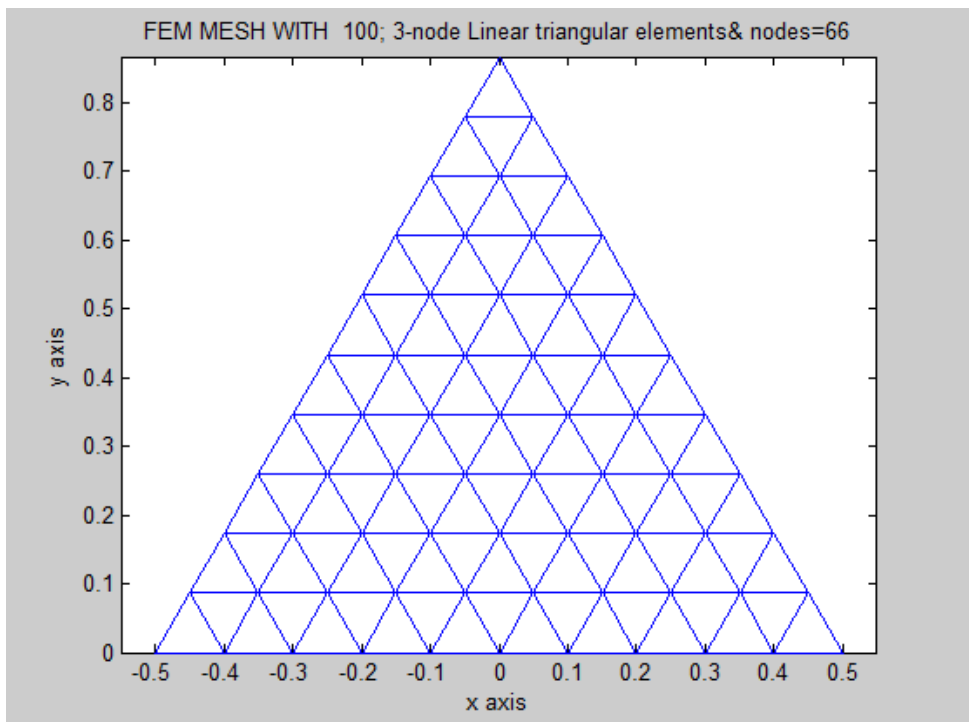
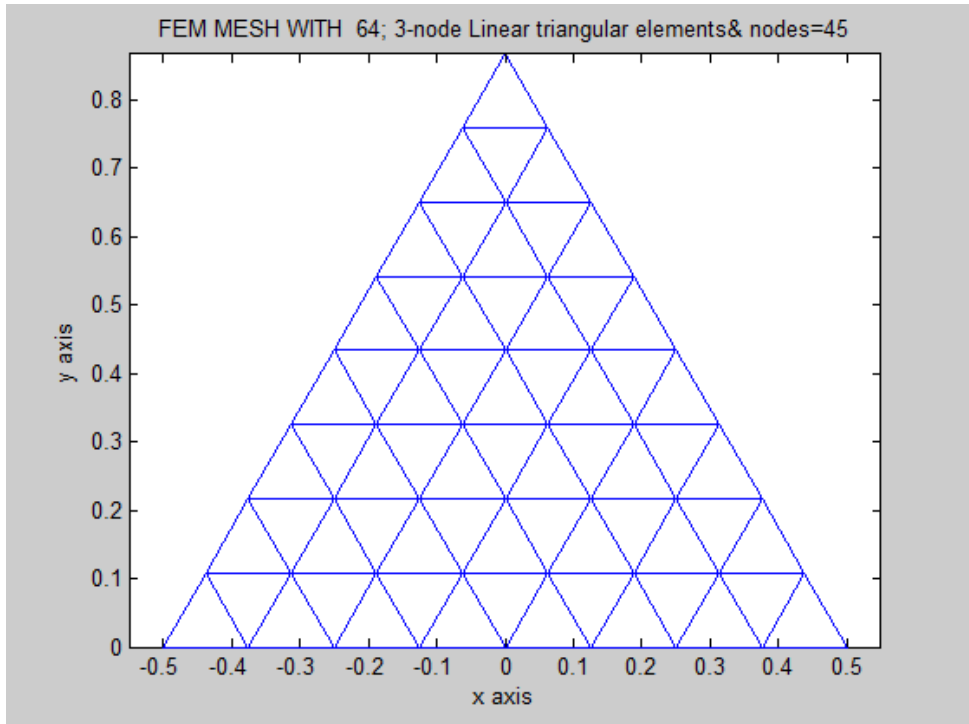


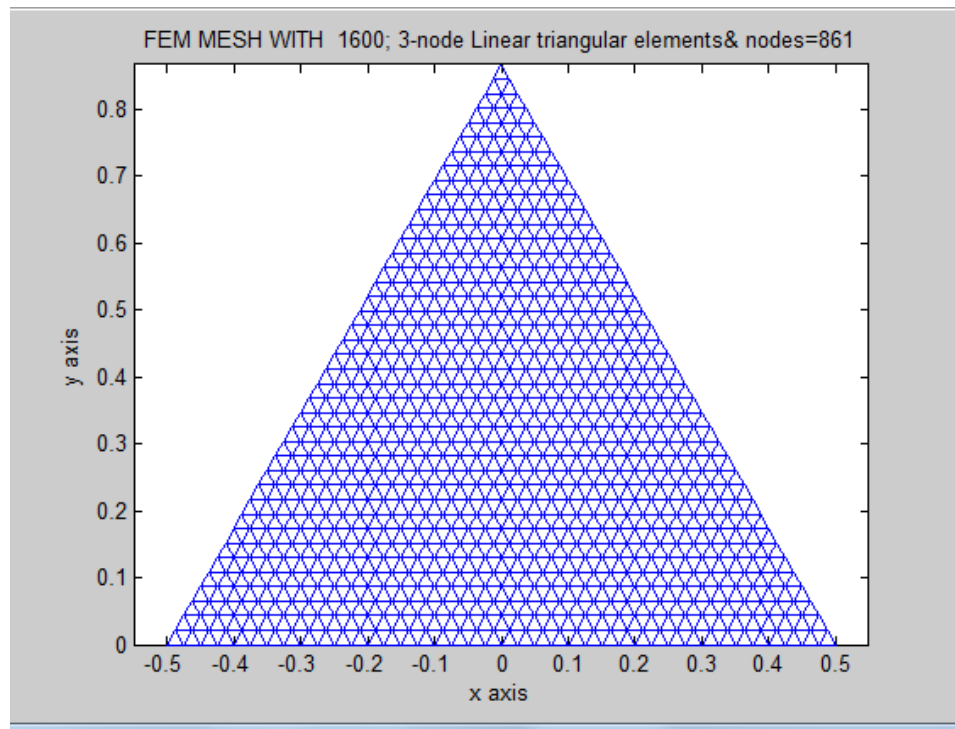
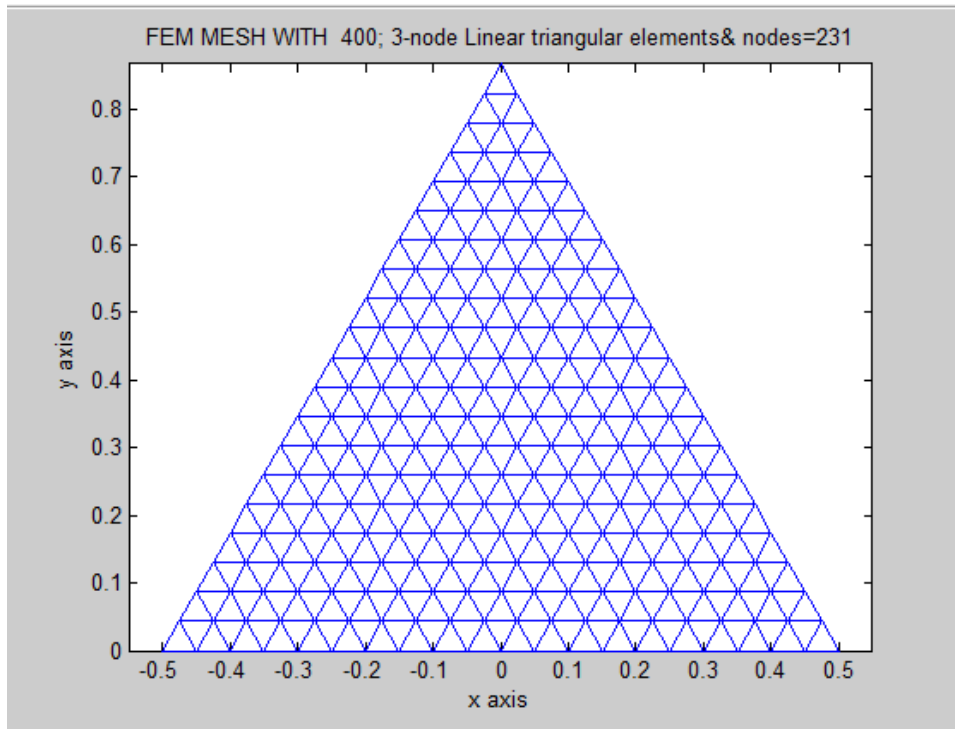
```
for iel=1:NEL
  for jel=1:3
    if(tnodes(iel,jel)>nnmax)
      tnodes(iel,jel)=tnodes(iel,jel)-(ndelete-1);
    end
  end
end
end
end
tnodes
```

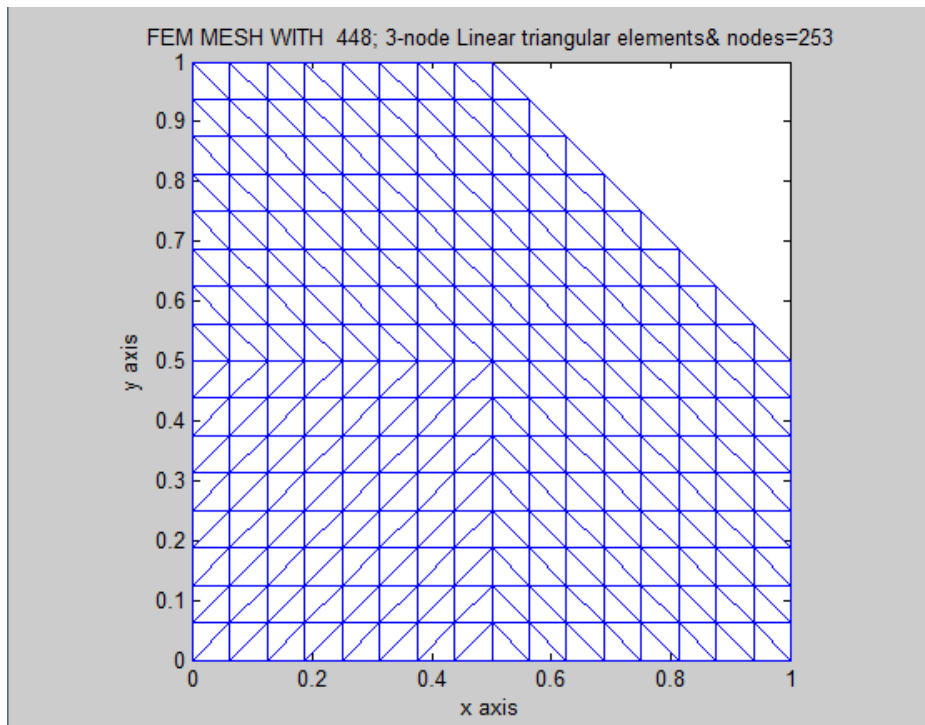
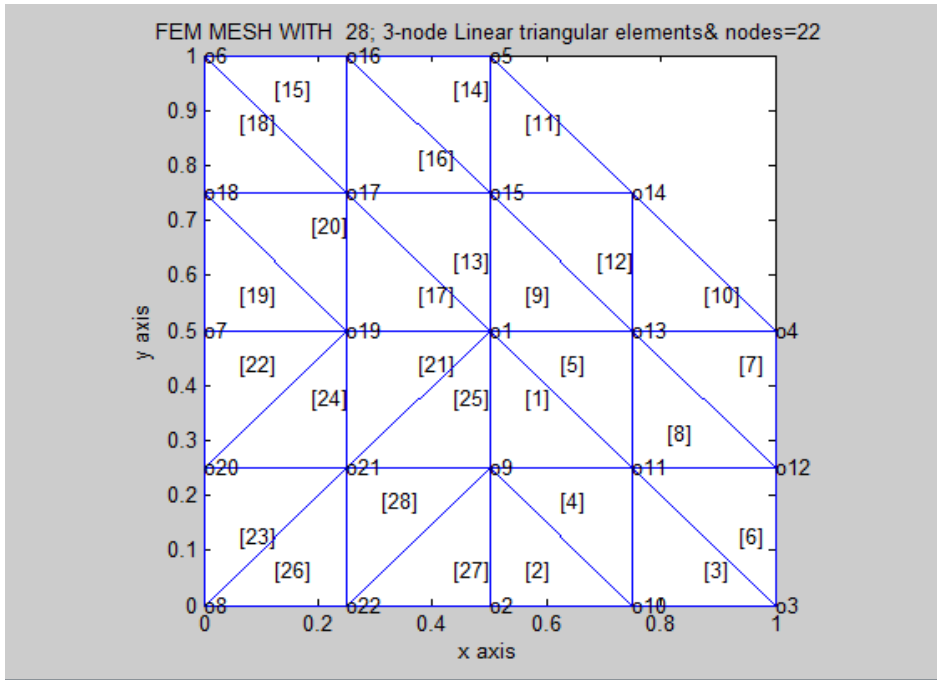
```
%=====
FIGURES
```

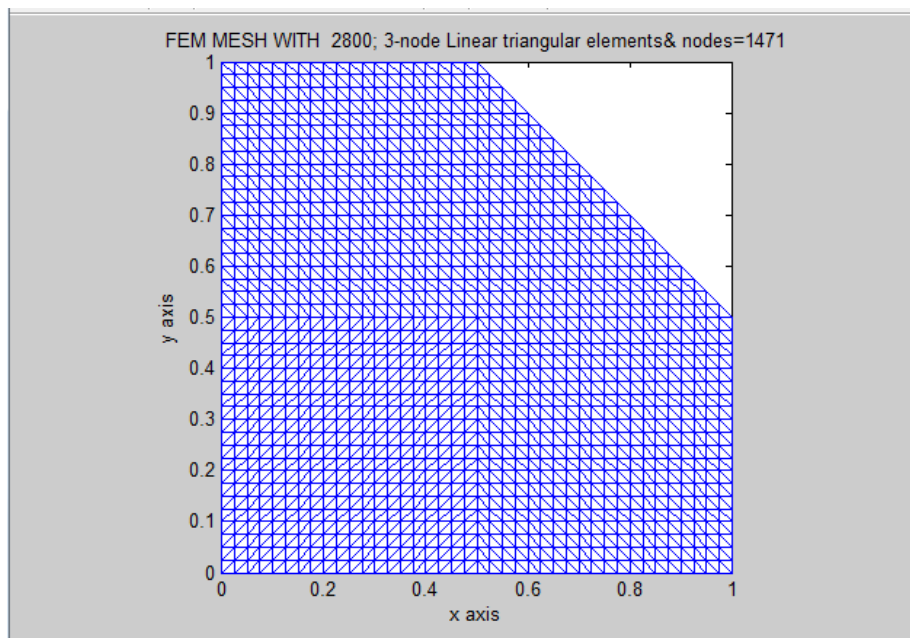
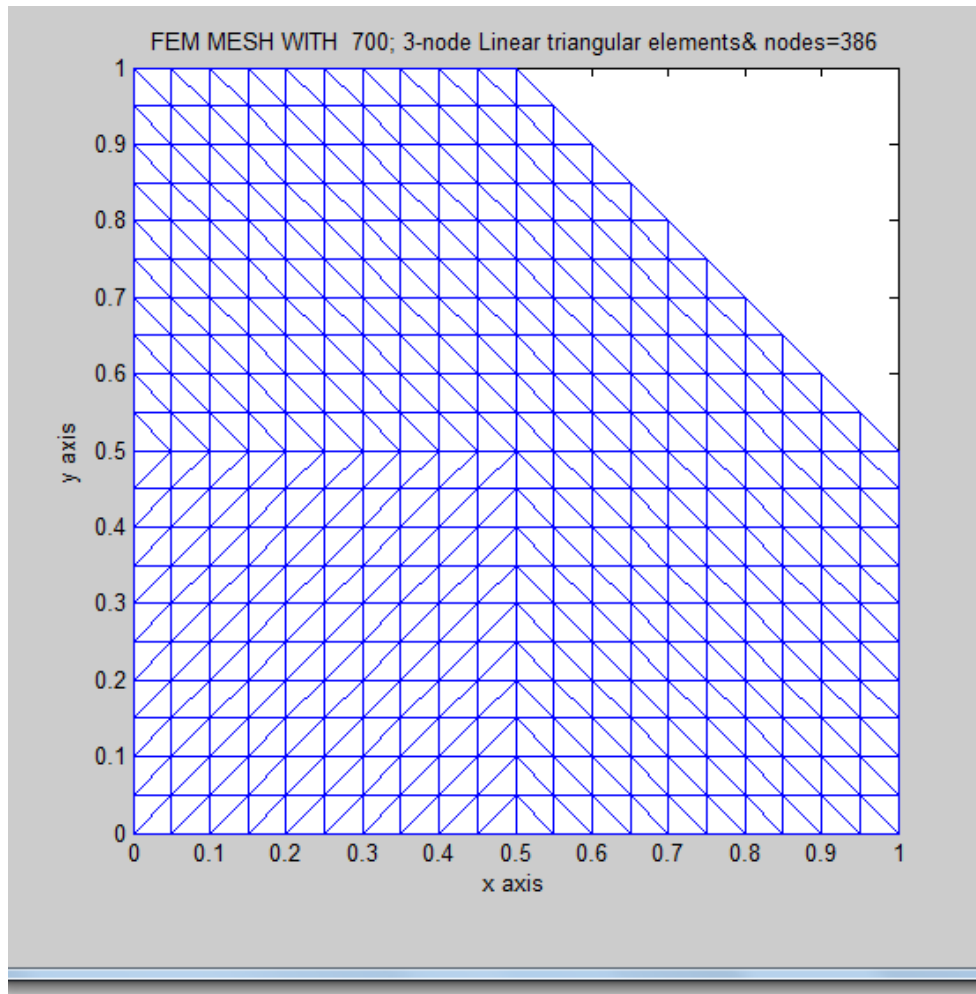


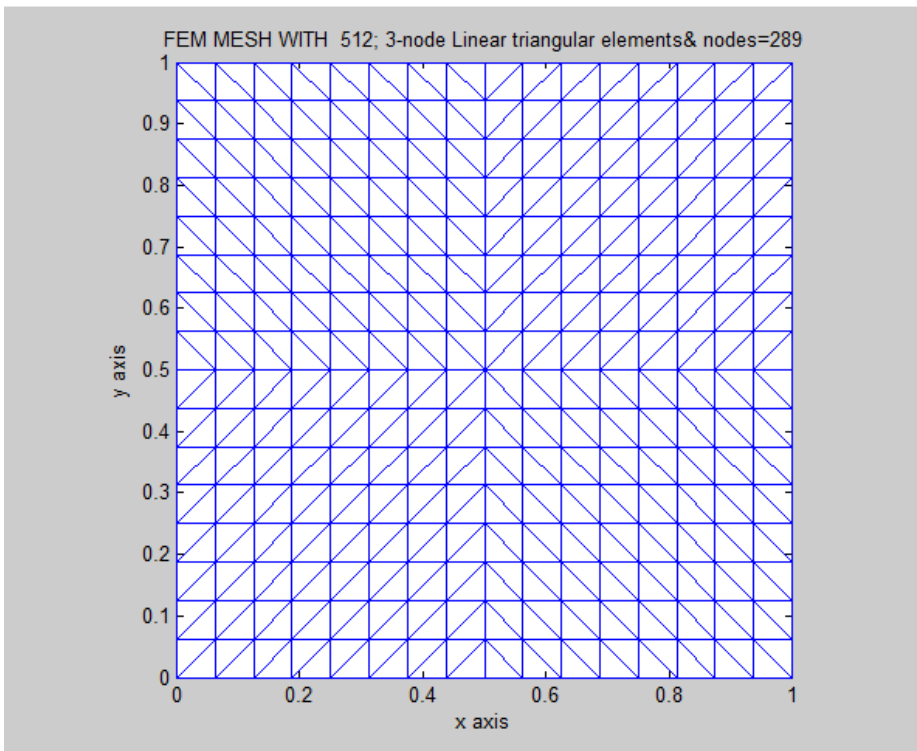
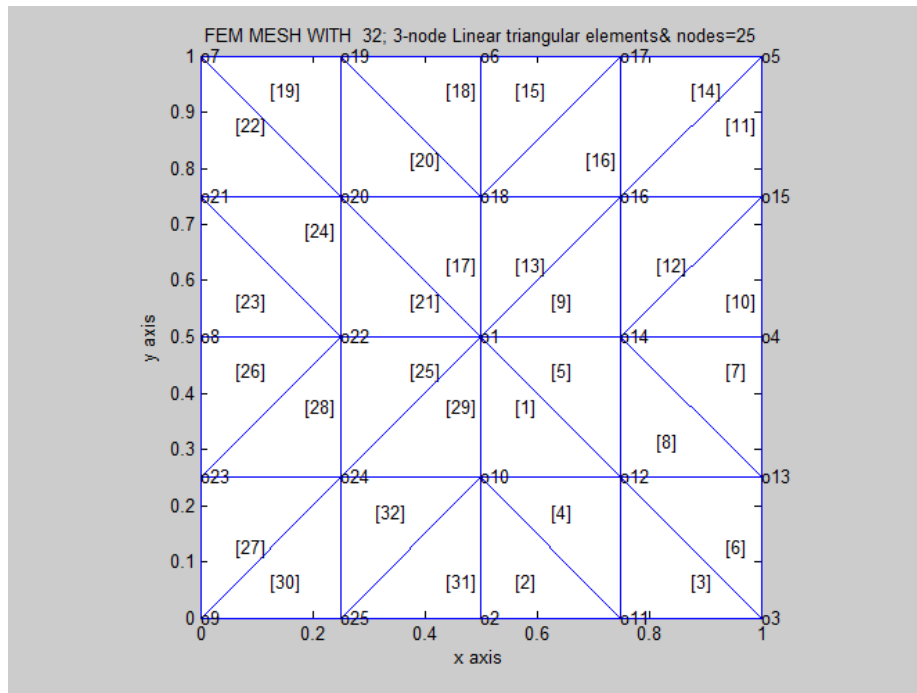


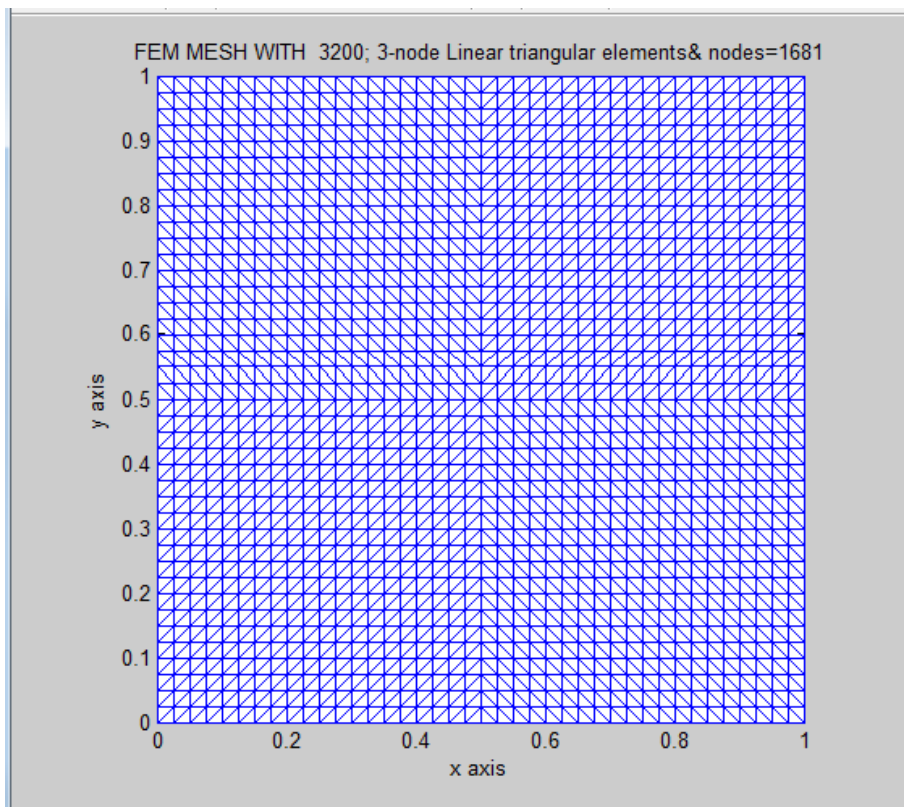
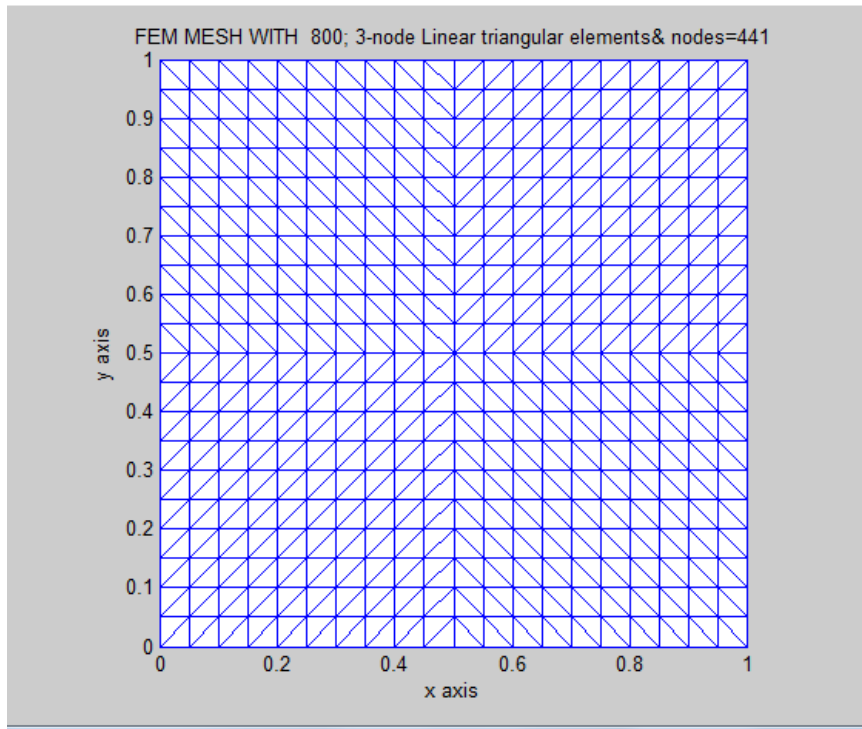




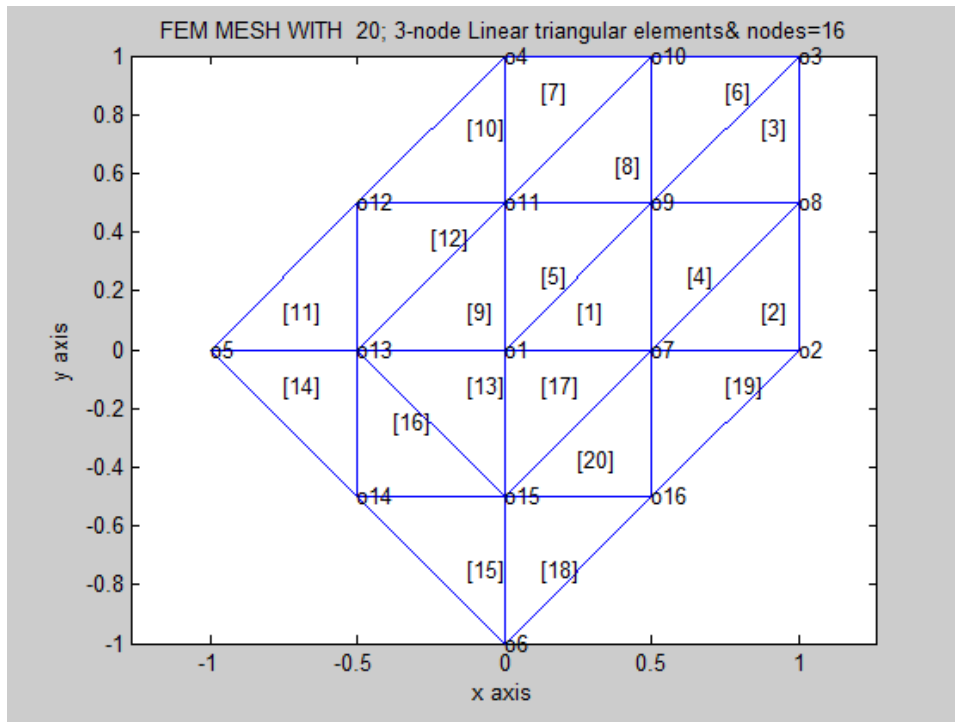






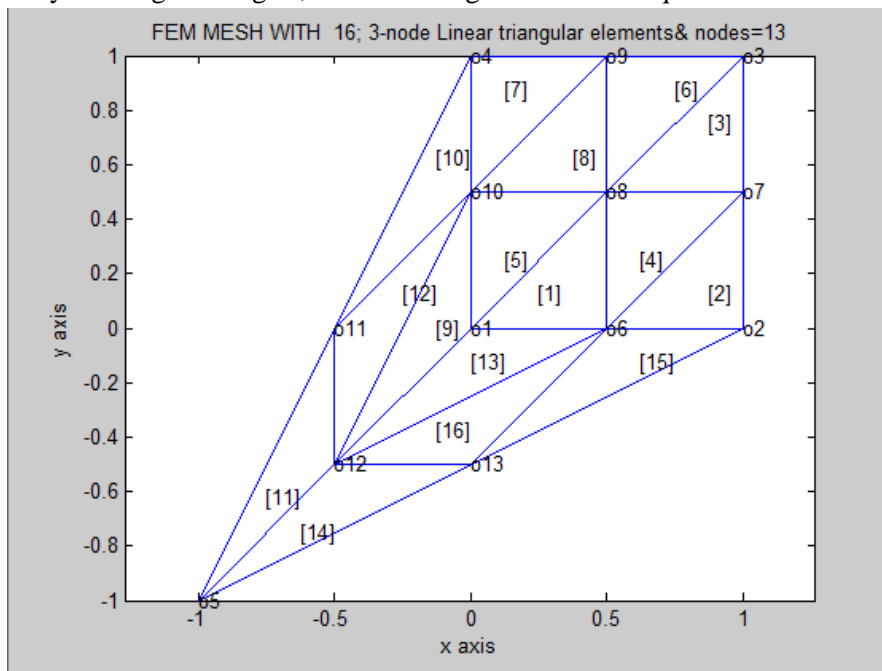


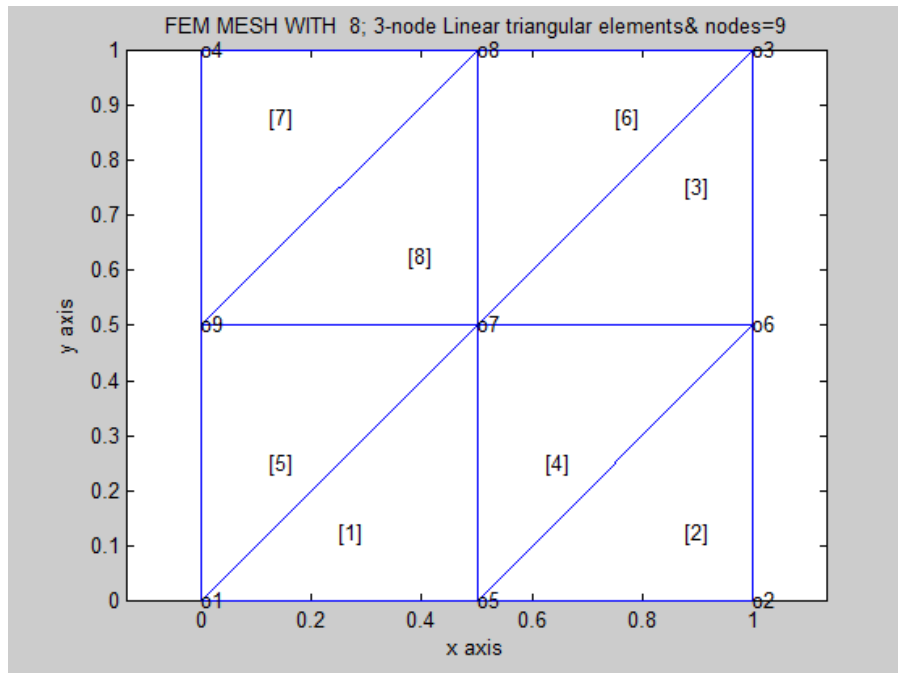




By setting  $n_{delete}=3$ , i.e. by deleting 3-triangles in the above, we can get a 1-square .

In a similar manner by deleting 2-triangles, we can also get the same 1-square from the following quadrilateral .





Using  $n_{delete}=3$ , i.e. by deleting 3 triangular elements from the coarse mesh of 5- triangles in the above and  $n_{delete}=2$ , we have shown that it is possible to create meshes for 1-squares, a very useful concept for cracked polygons shown later here for icosagon in the end

